



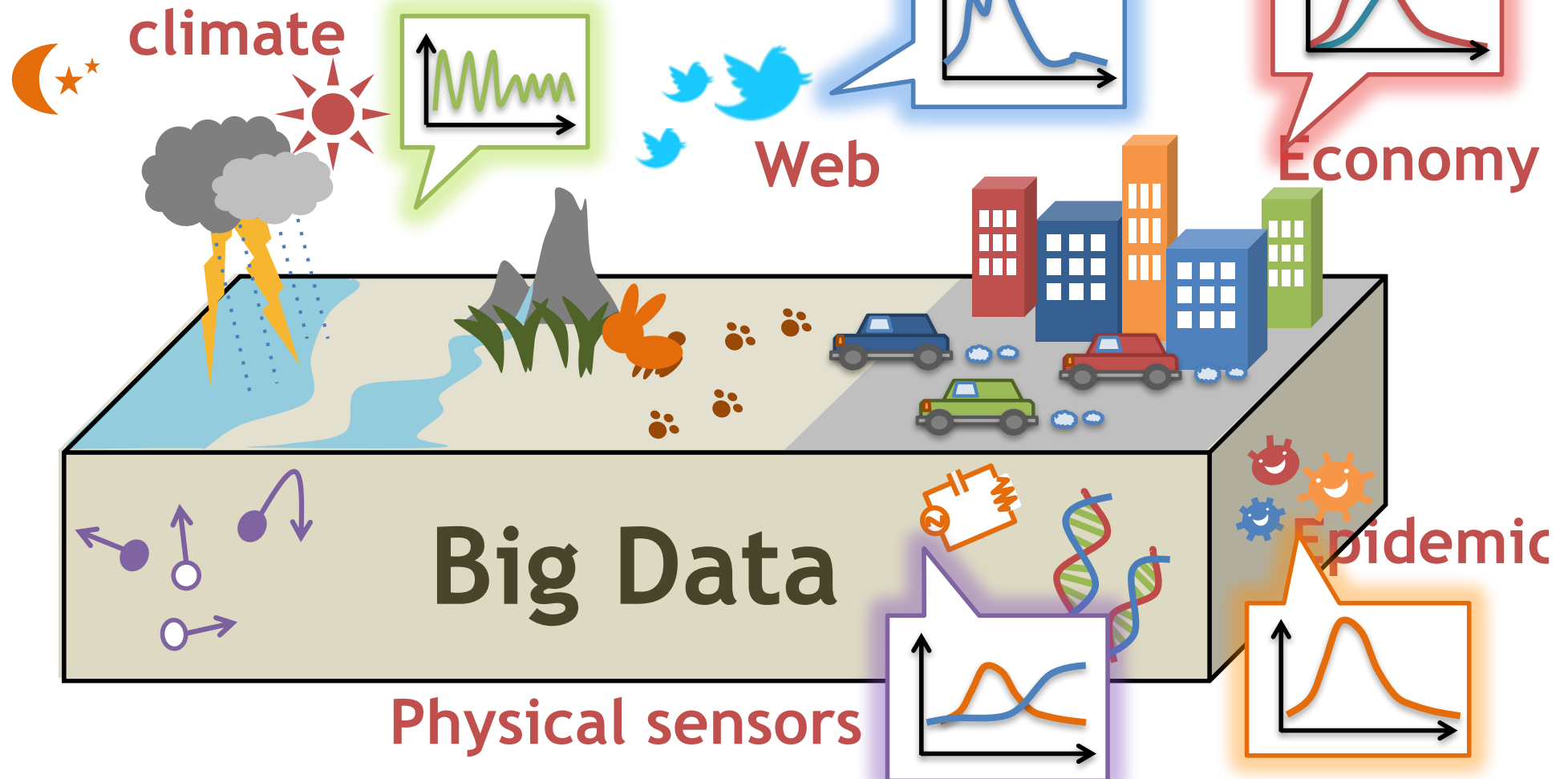
Regime Shifts in Streams: Real-time Forecasting of Co-evolving Time Sequences

Yasuko Matsubara, Yasushi Sakurai
(Kumamoto University)



Big time-series data streams

Social/natural phenomena



Big time-series data streams

Social/natural phenomena

climate

Motion sensors

L/R legs

L/R arms

(walking)

Physical sensors

Economy

Epidemic

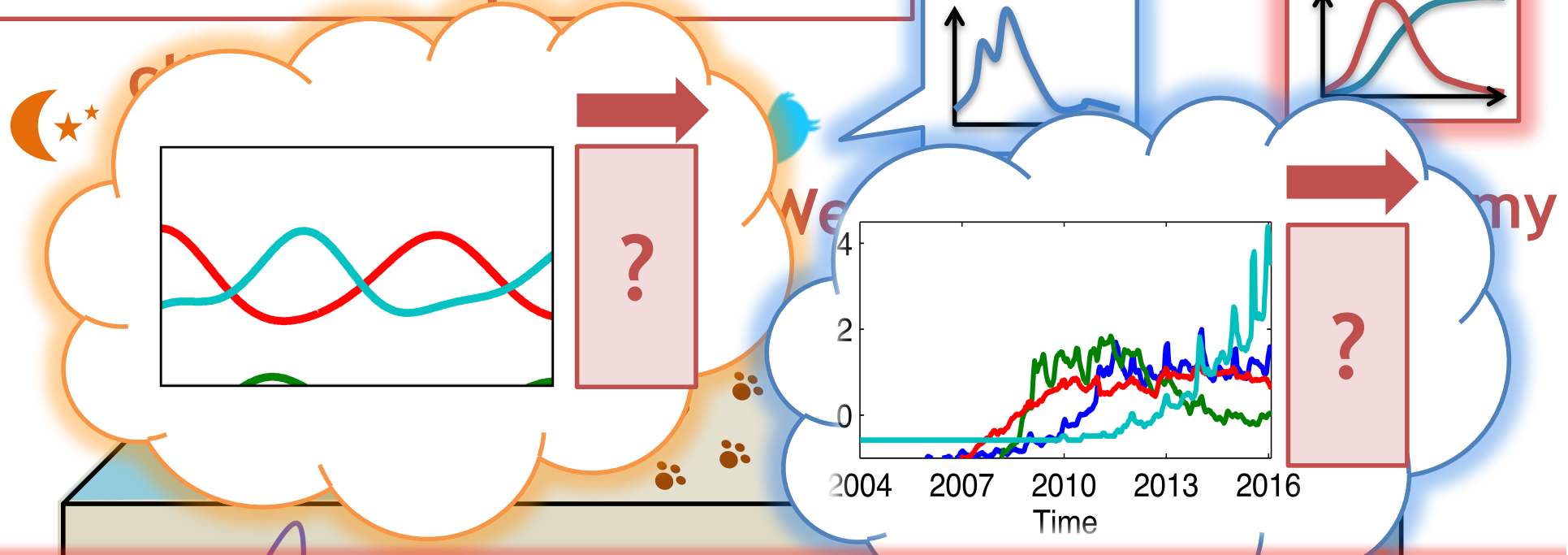
Big time-series data streams

Social/natural phenomena



Big time-series data streams

Social/natural phenomena



Big Data

Q. Can we forecast future events?

Physical sensors

Big time-series data streams

- **Given:**

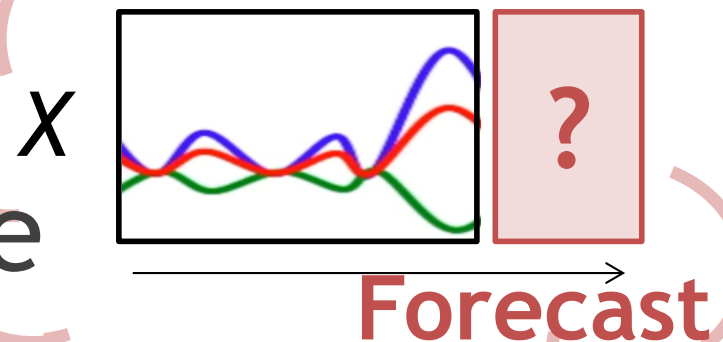
Co-evolving event stream

$$X = \{x(1), x(2), \dots, x(t_c), \dots\}$$

- **Goal:**

Forecast l_s -steps-ahead

future events,
at any point in time



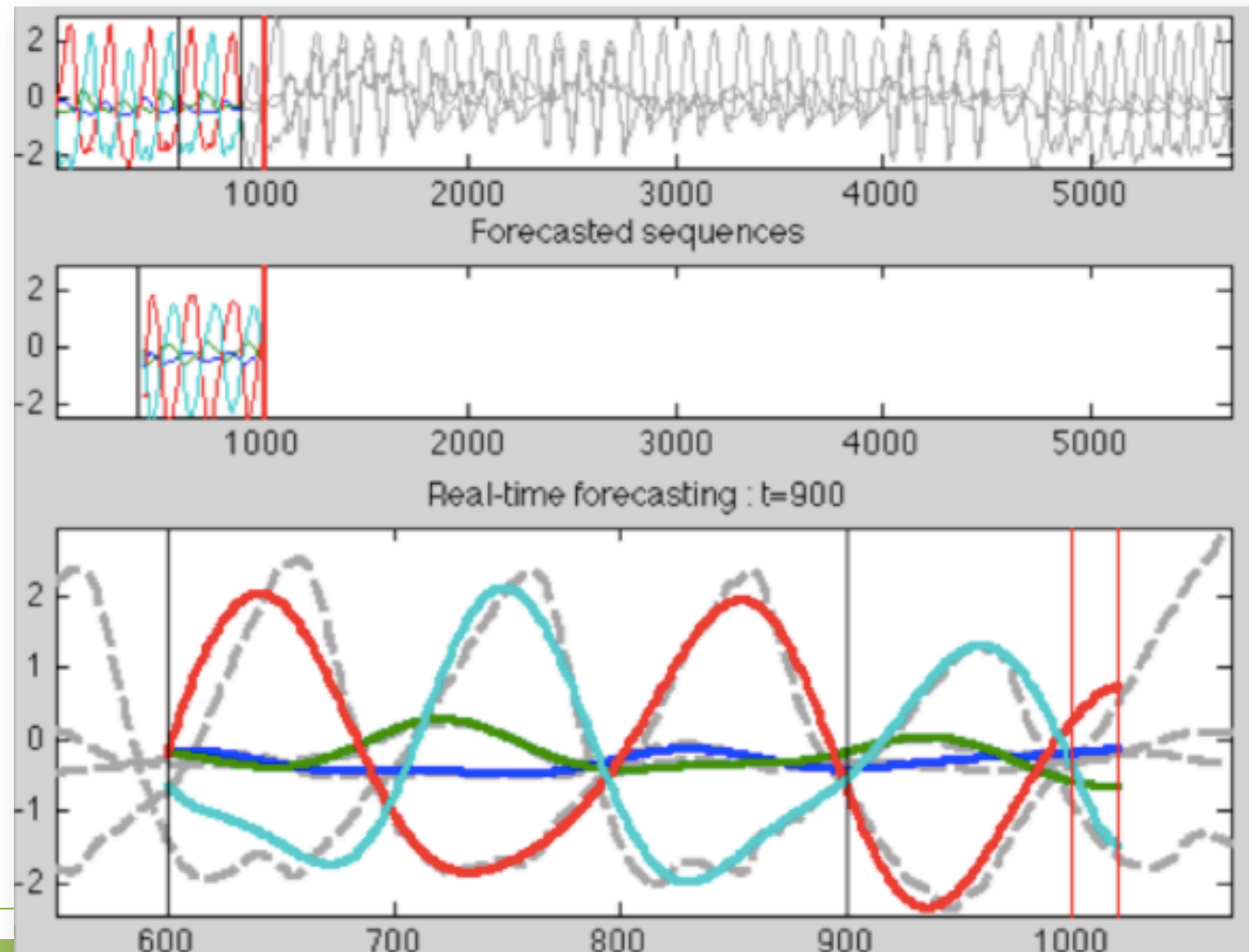
Roadmap

- ✓ Motivation
 - Forecasting power of RegimeCast
 - Overview
 - Proposed model
 - Streaming algorithm
 - Experiments
 - Conclusions



Forecasting power of RegimeCast

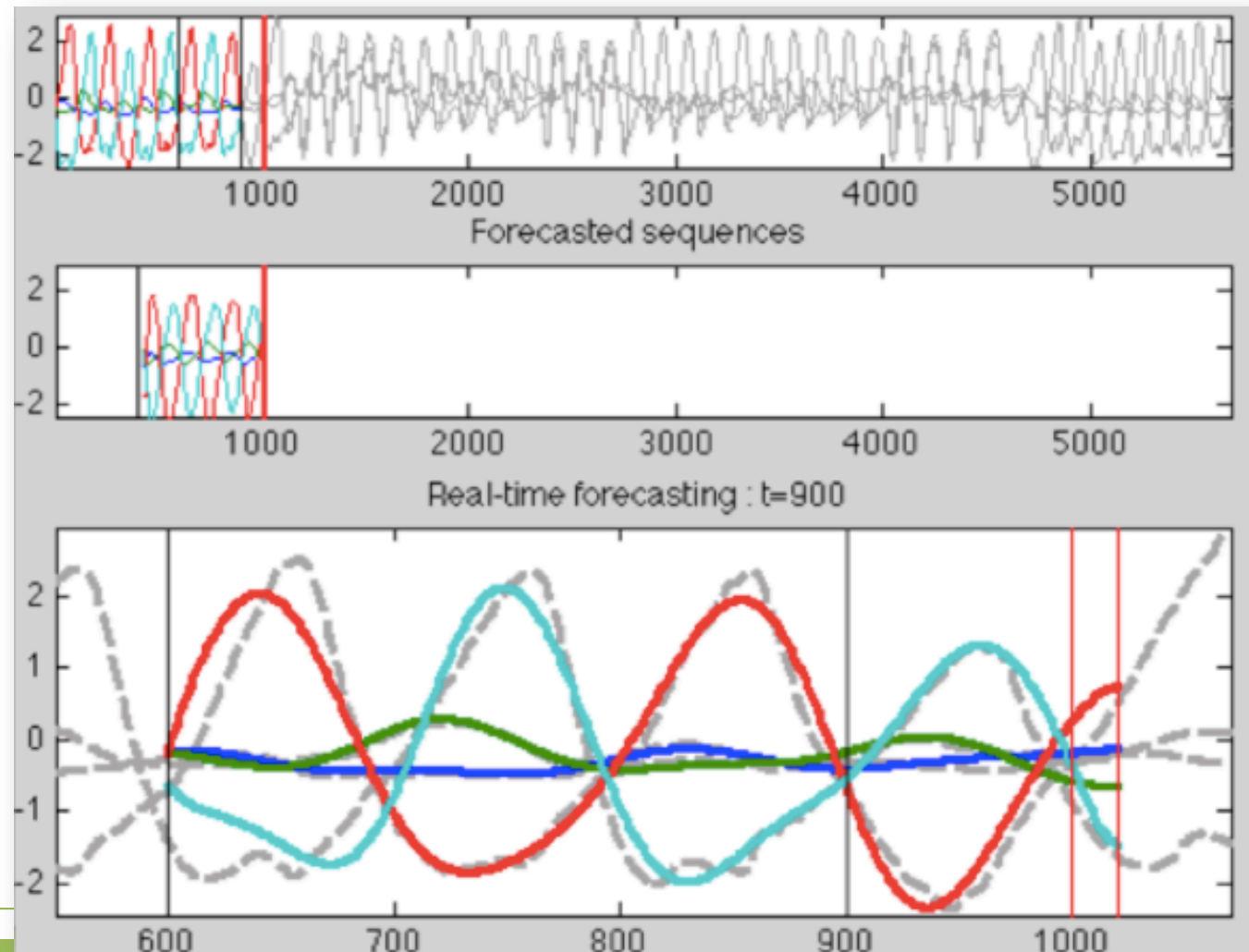
Real-time forecasting over data streams



Forecasting power of RegimeCast

Real-time forecasting over data streams

Original



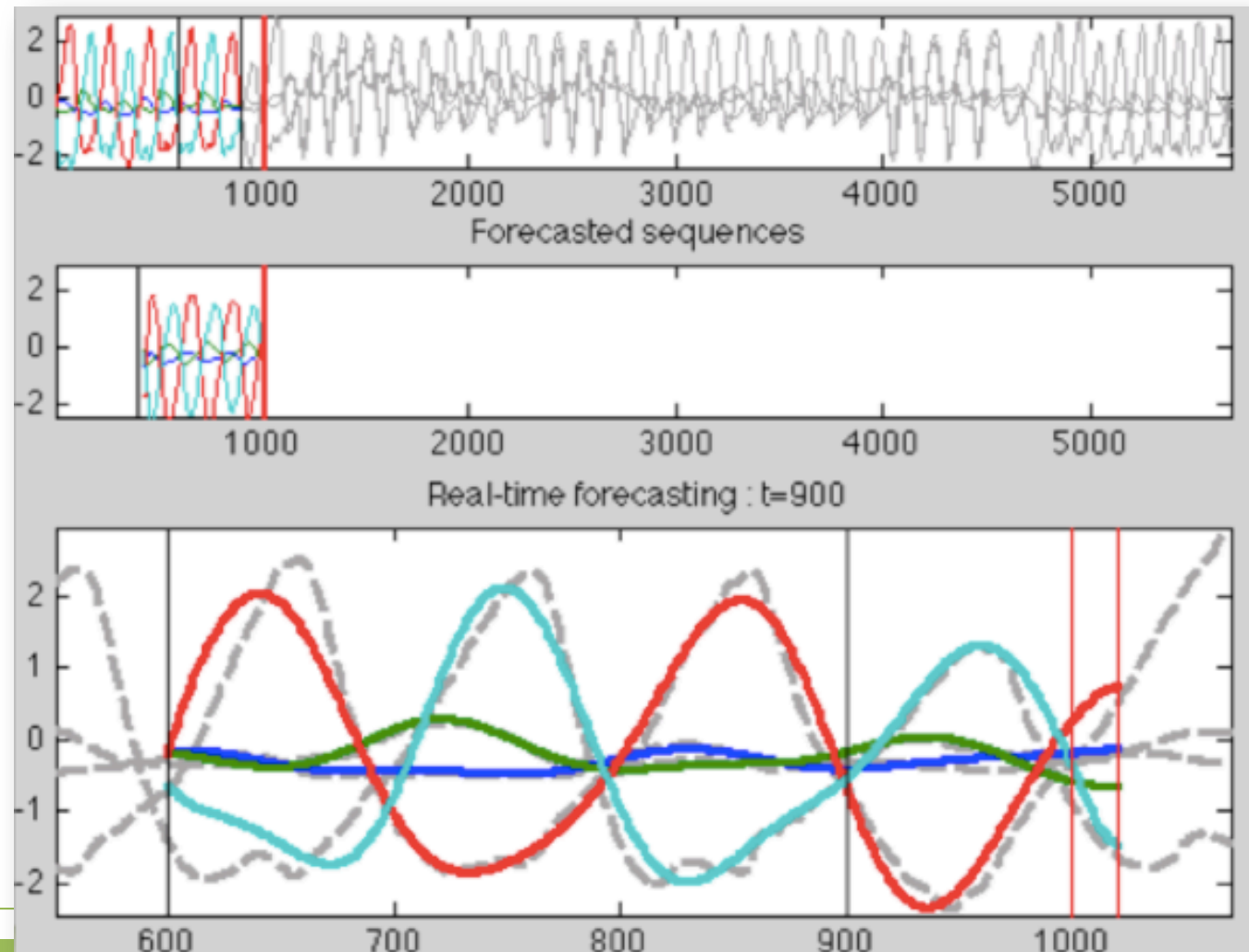
Forecasting power of RegimeCast

Real-time forecasting over data streams

Original

Forecast

(100-steps
-ahead)



Forecasting power of RegimeCast

Real-time forecasting over data streams

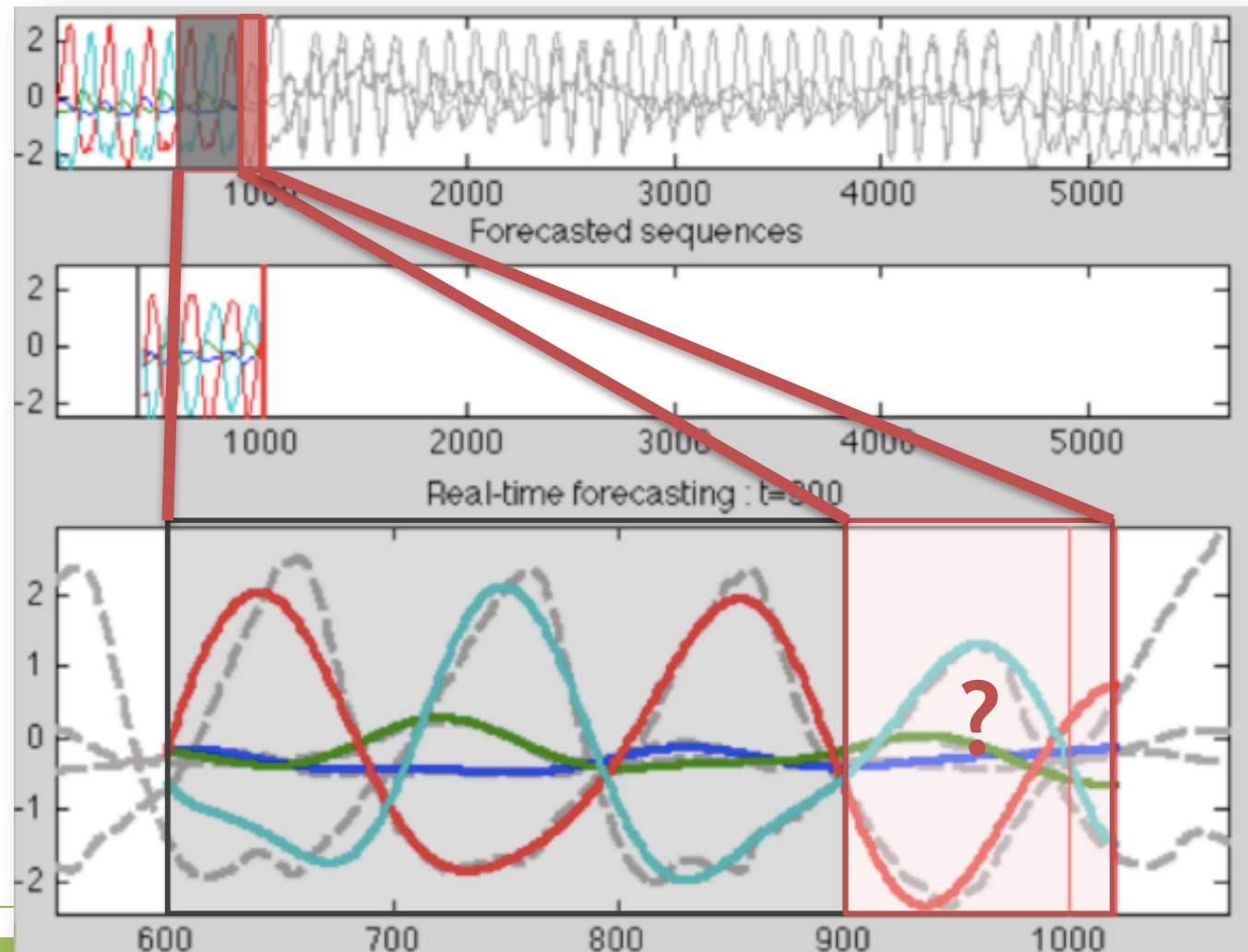
Original

Forecast

(100-steps
-ahead)

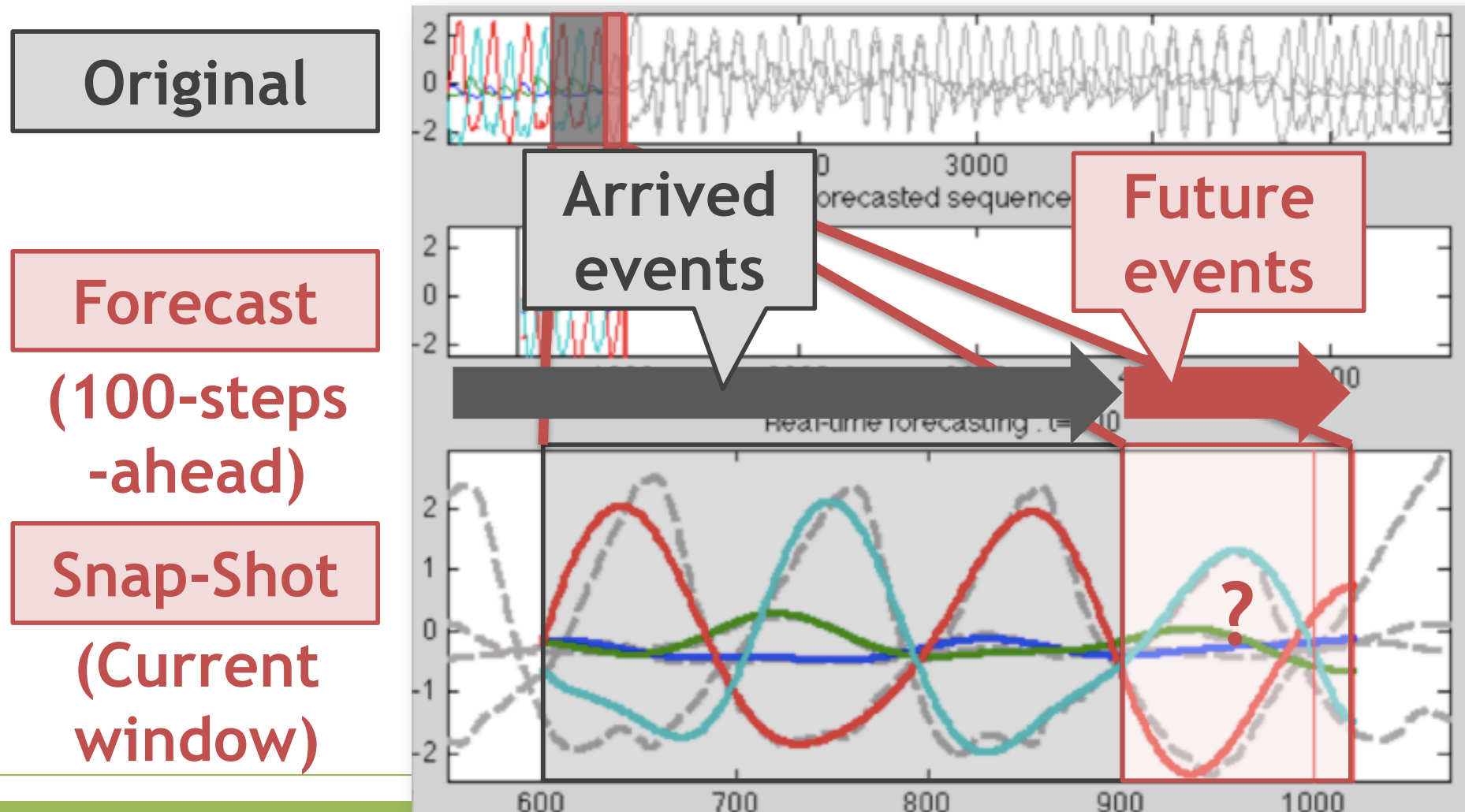
Snap-Shot

(Current
window)



Forecasting power of RegimeCast

Real-time forecasting over data streams



Forecasting power of RegimeCast

Real-time forecasting over

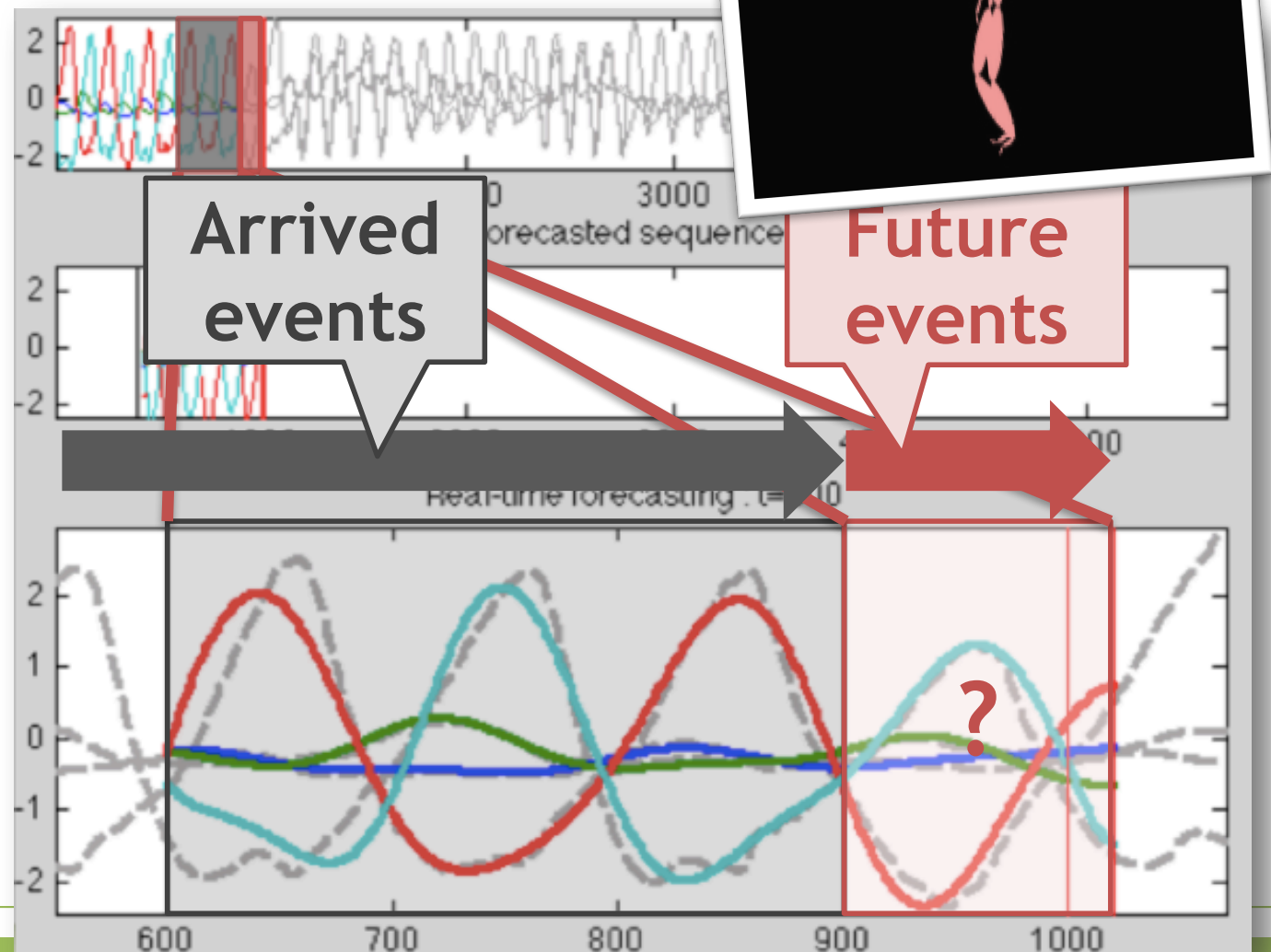
Original

Forecast

(100-steps
-ahead)

Snap-Shot

(Current
window)



Forecasting power of RegimeCast

Real-time forecasting over data streams

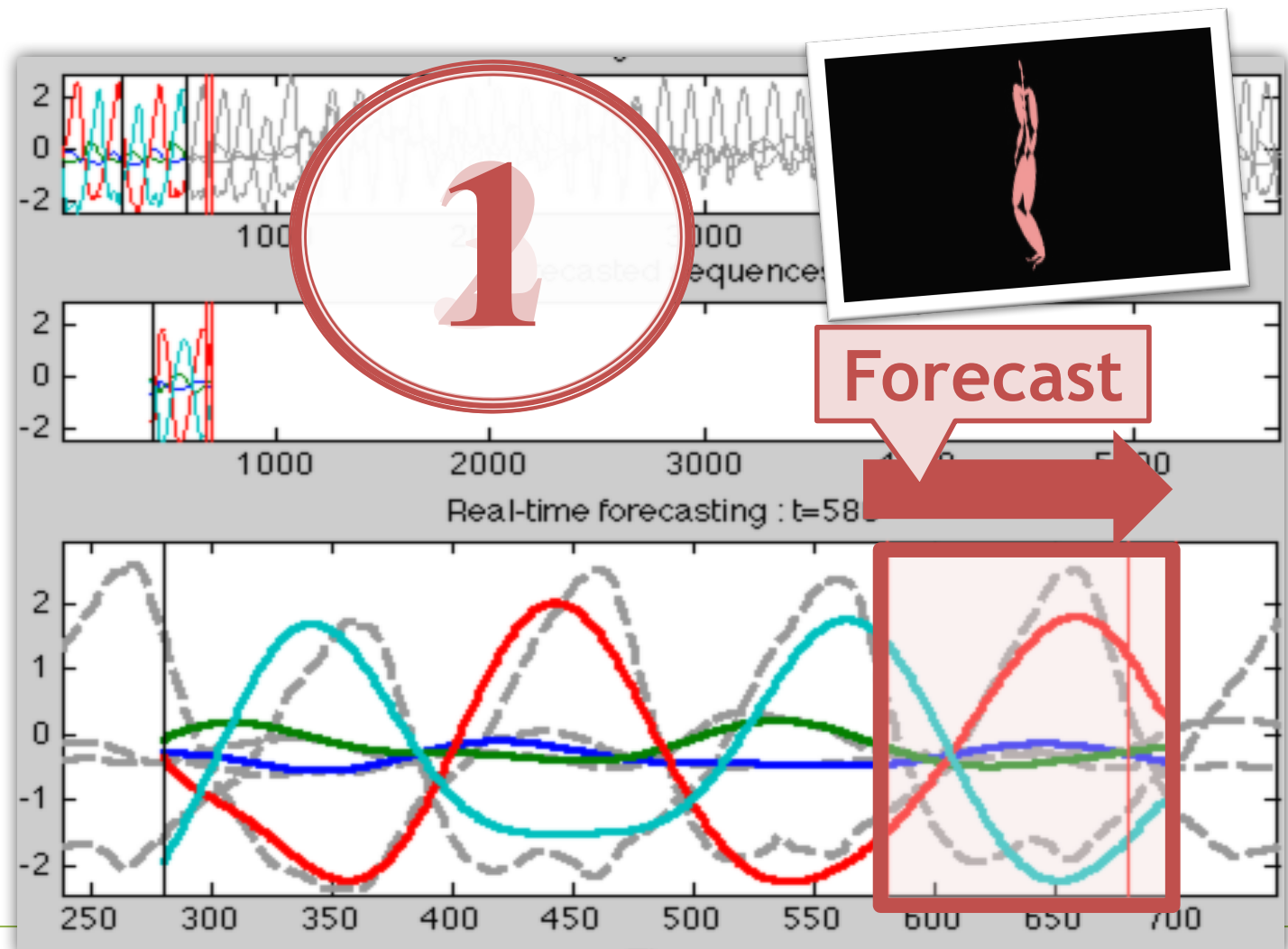
Original

Forecast

(100-steps
-ahead)

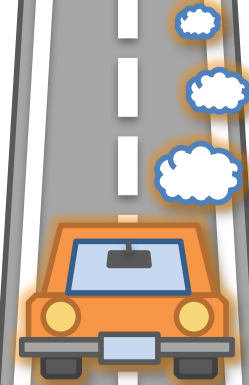
Snap-Shot

(Current
window)



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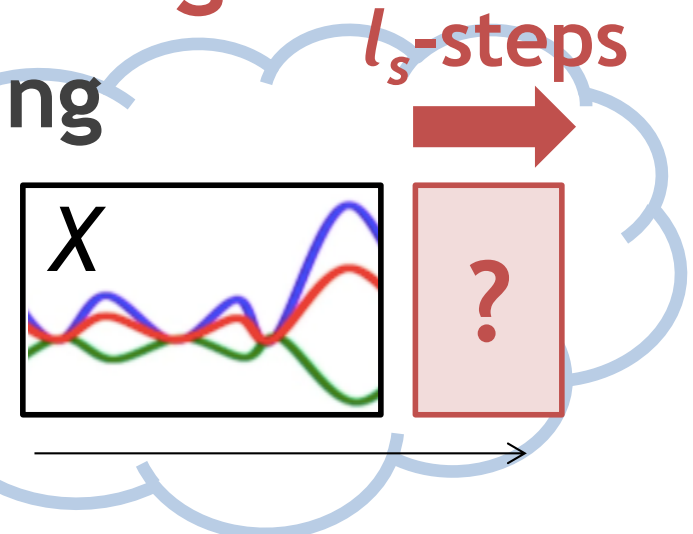
Overview

What is “Real-time forecasting”?

(a) l_s -steps-ahead forecasting

Long-term

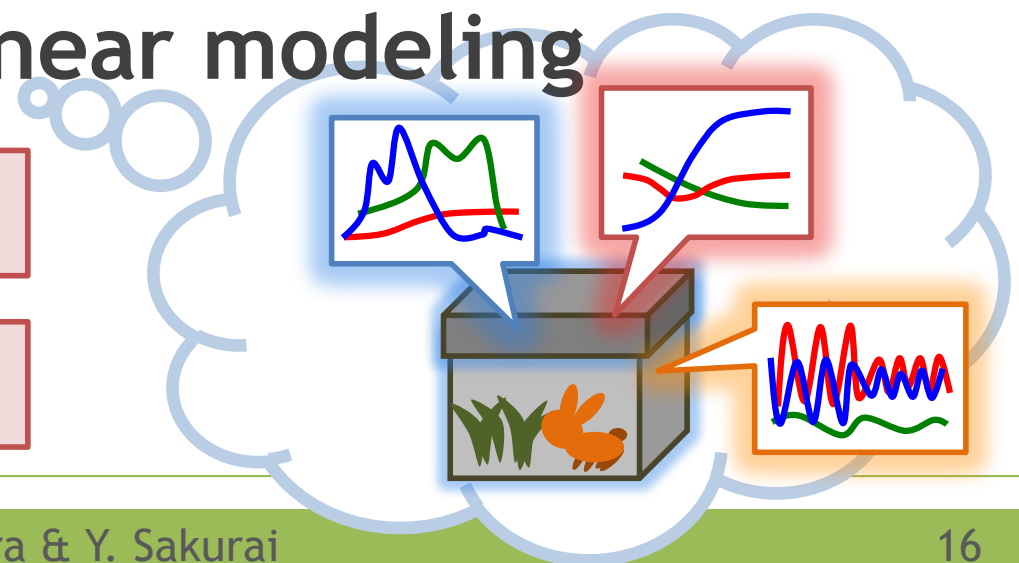
Continuous



(b) Adaptive non-linear modeling

Non-linear

Adaptive



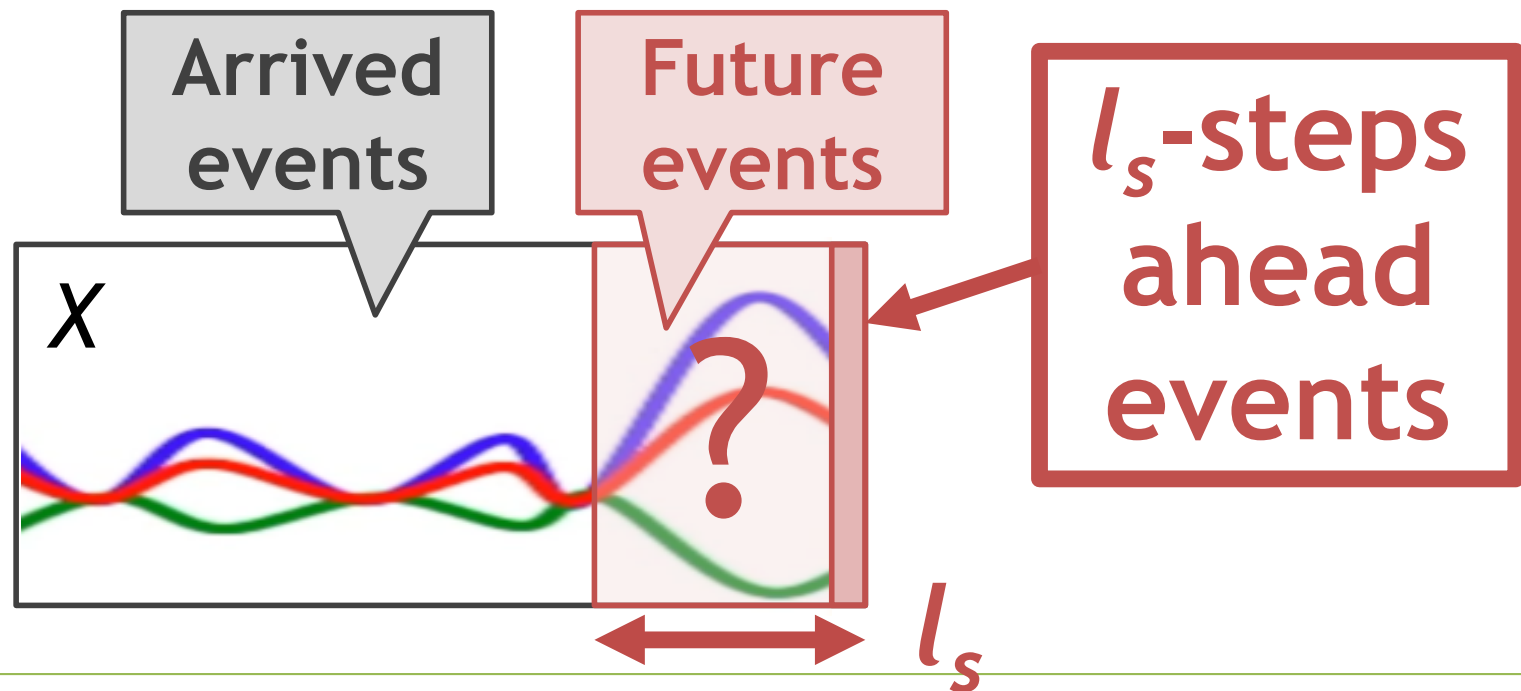
(a) l_s -steps-ahead forecasting

Long-term

: Predict l_s -steps ahead events

Continuous

: Capture dynamic patterns



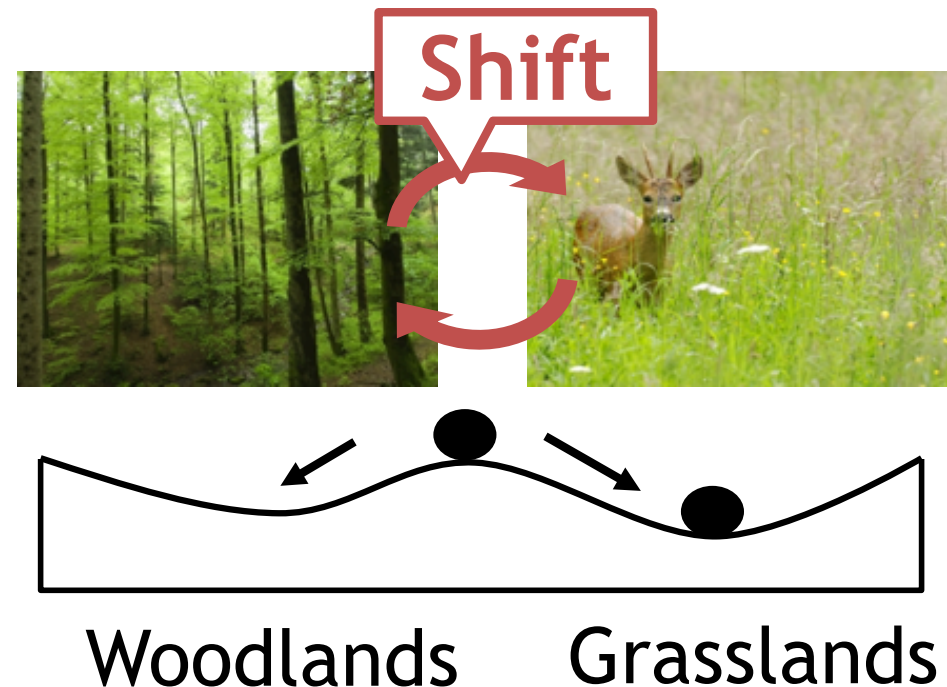
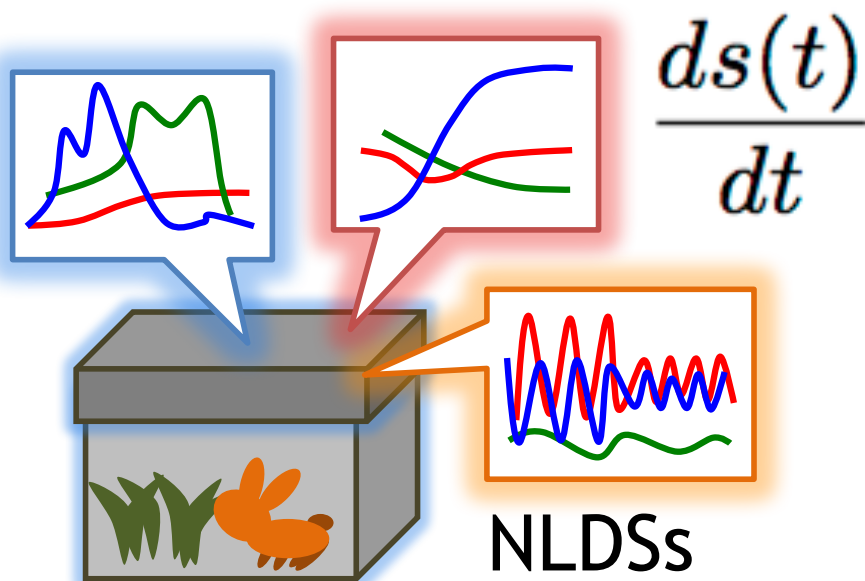
(b) Adaptive non-linear modeling

Non-linear

: Non-linear dynamical systems

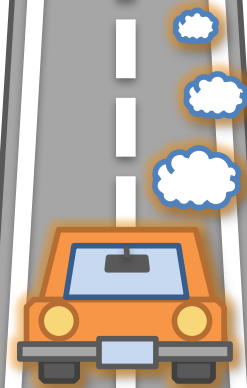
Adaptive

: Regime shifts (ecosystems)



Roadmap

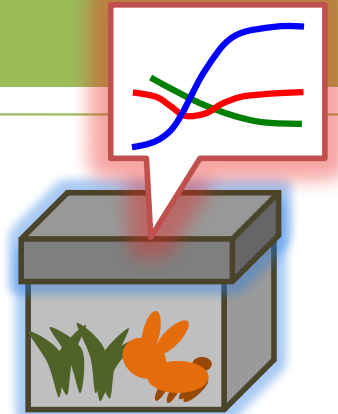
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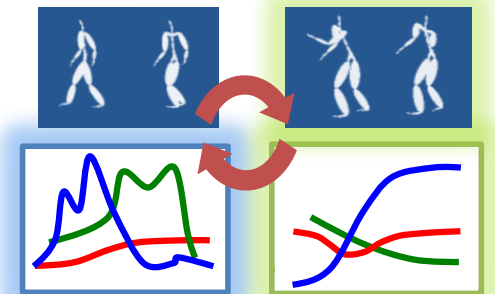
Proposed model

Main ideas

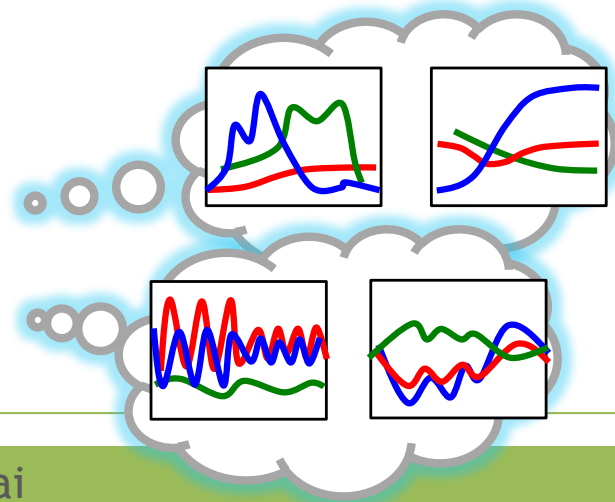
P1 Latent non-linear dynamics



P2 Regime shifts in streams



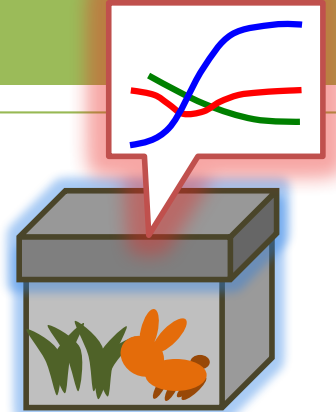
P3 Nested structure



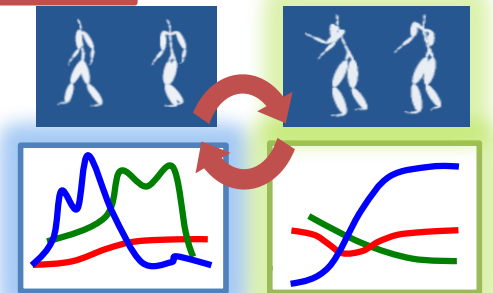
Proposed model

Main ideas

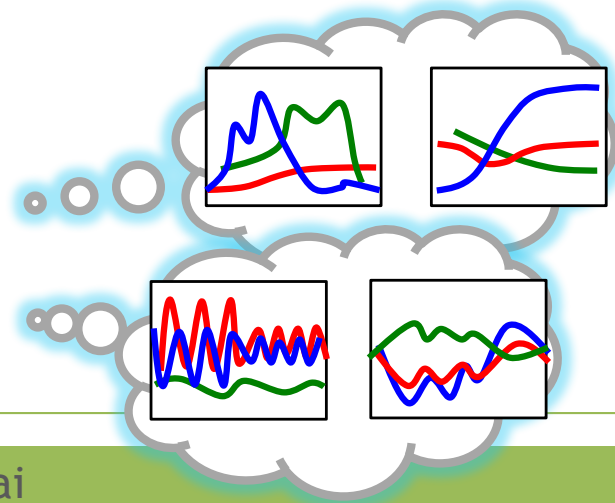
P1 Latent non-linear dynamics



P2 Regime shifts in streams

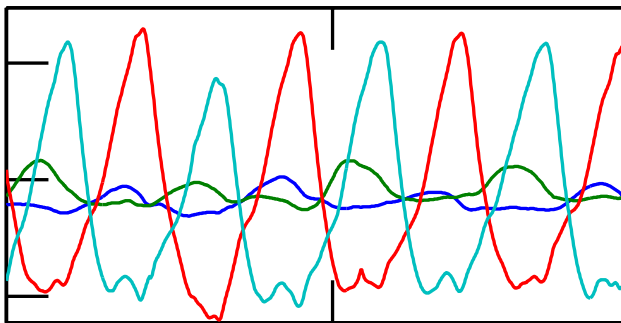


P3 Nested structure

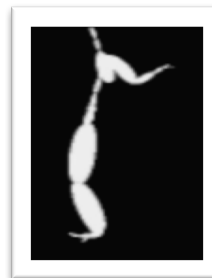
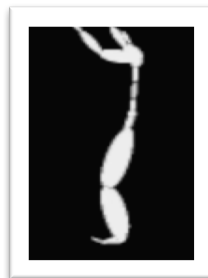
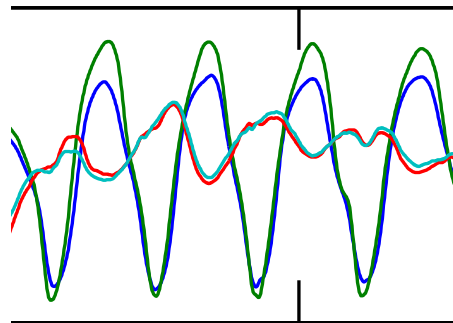


Various patterns (“**regimes**”) in streams

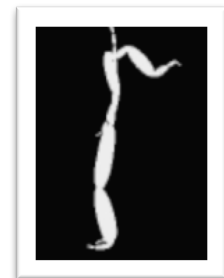
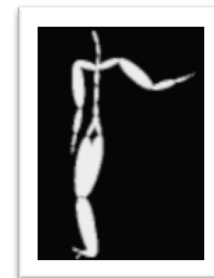
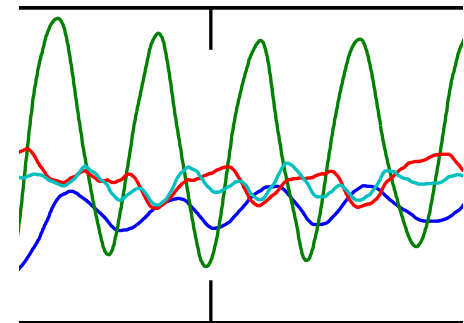
walking



stretching

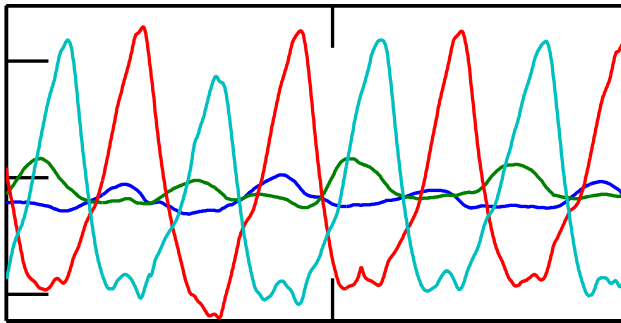


(right)

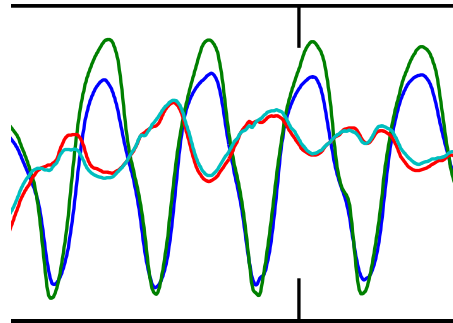


Various patterns (“**regimes**”) in streams

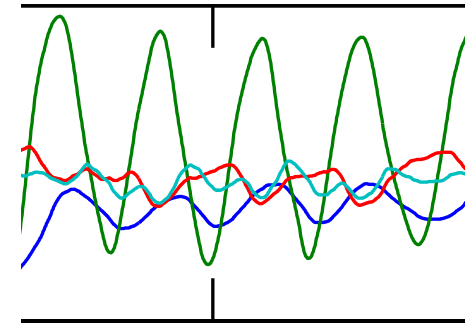
walking



stretching



(right)



Q. How can we effectively capture dynamics of “regimes”?

Details

A. Latent NLDS

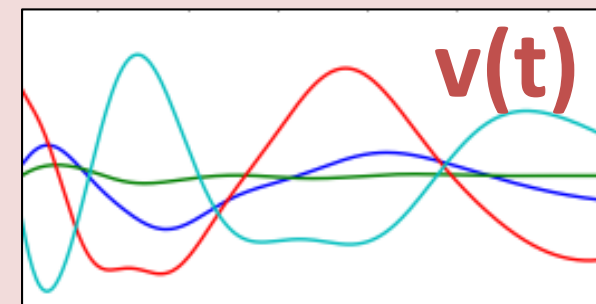
$$\frac{ds(t)}{dt} = \mathbf{p} + \mathbf{Q}s(t) + \mathcal{A}\mathbf{S}(t)$$

$$\mathbf{v}(t) = \mathbf{u} + \mathbf{V}s(t)$$

Potential activity



Estimated event



Details

A. Latent NLDS

Linear Exponential Non-linear

$$\frac{ds(t)}{dt} = p + Qs(t) + As(t)$$

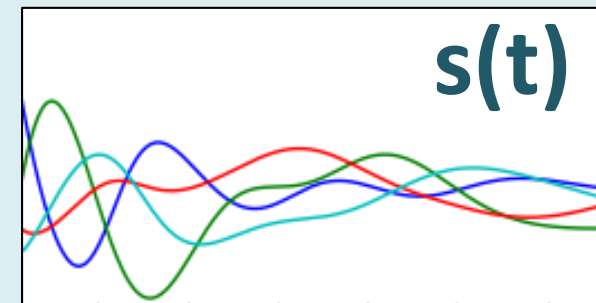
$$v(t) = u + Vs(t)$$

* $S(0)=s_0$

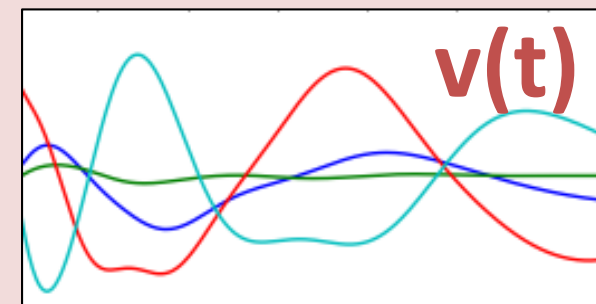
Projection

$$\theta = \{s_0, p, Q, A, u, V\}$$

Potential activity



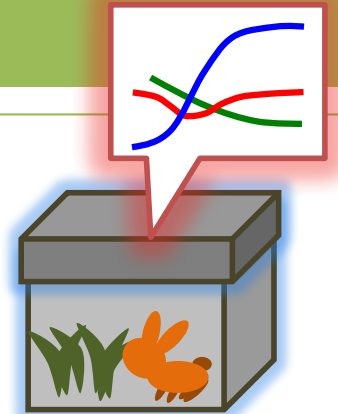
Estimated event



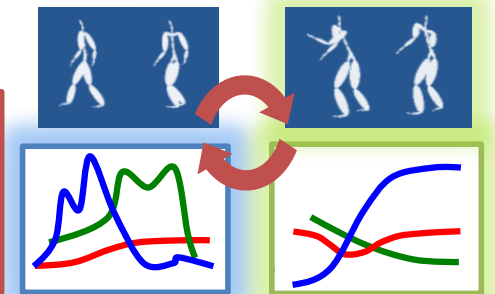
Proposed model

Main ideas

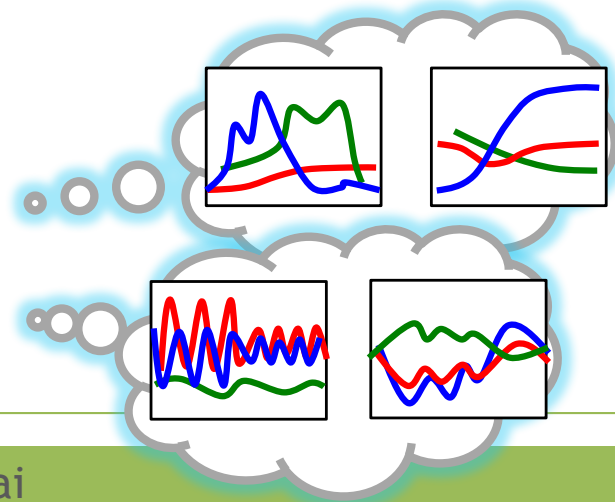
✓ **P1** Latent non-linear dynamics



P2 Regime shifts in streams



P3 Nested structure



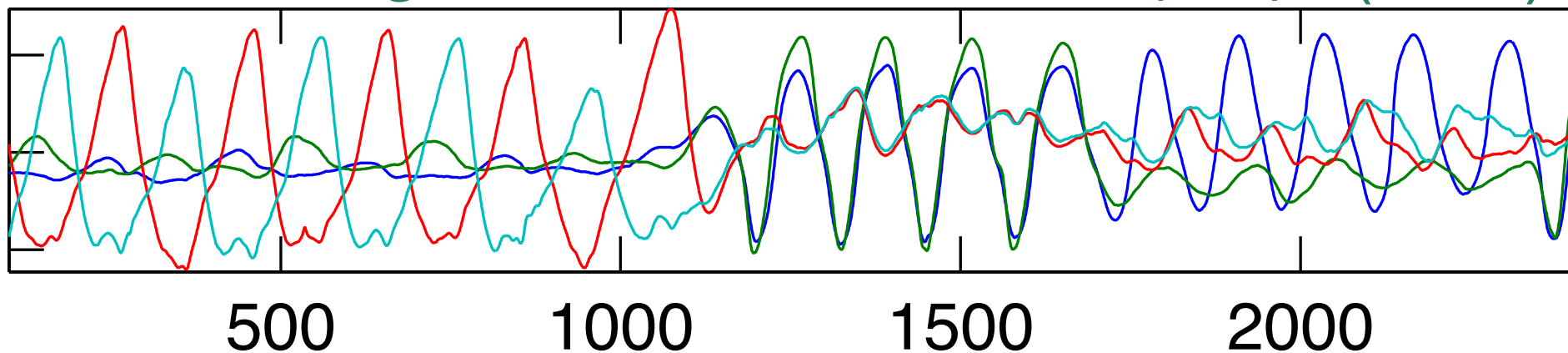
Regime shifts in streams

P2

Various patterns (“**regimes**”) in streams

walking

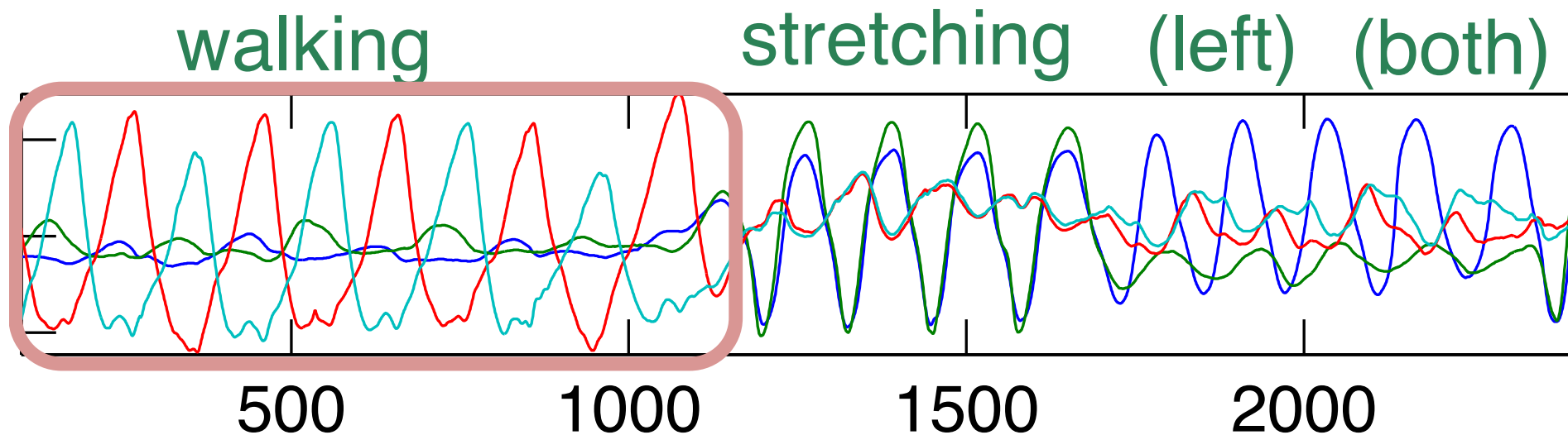
stretching (left) (both)



Regime shifts in streams

P2

Various patterns (“**regimes**”) in streams



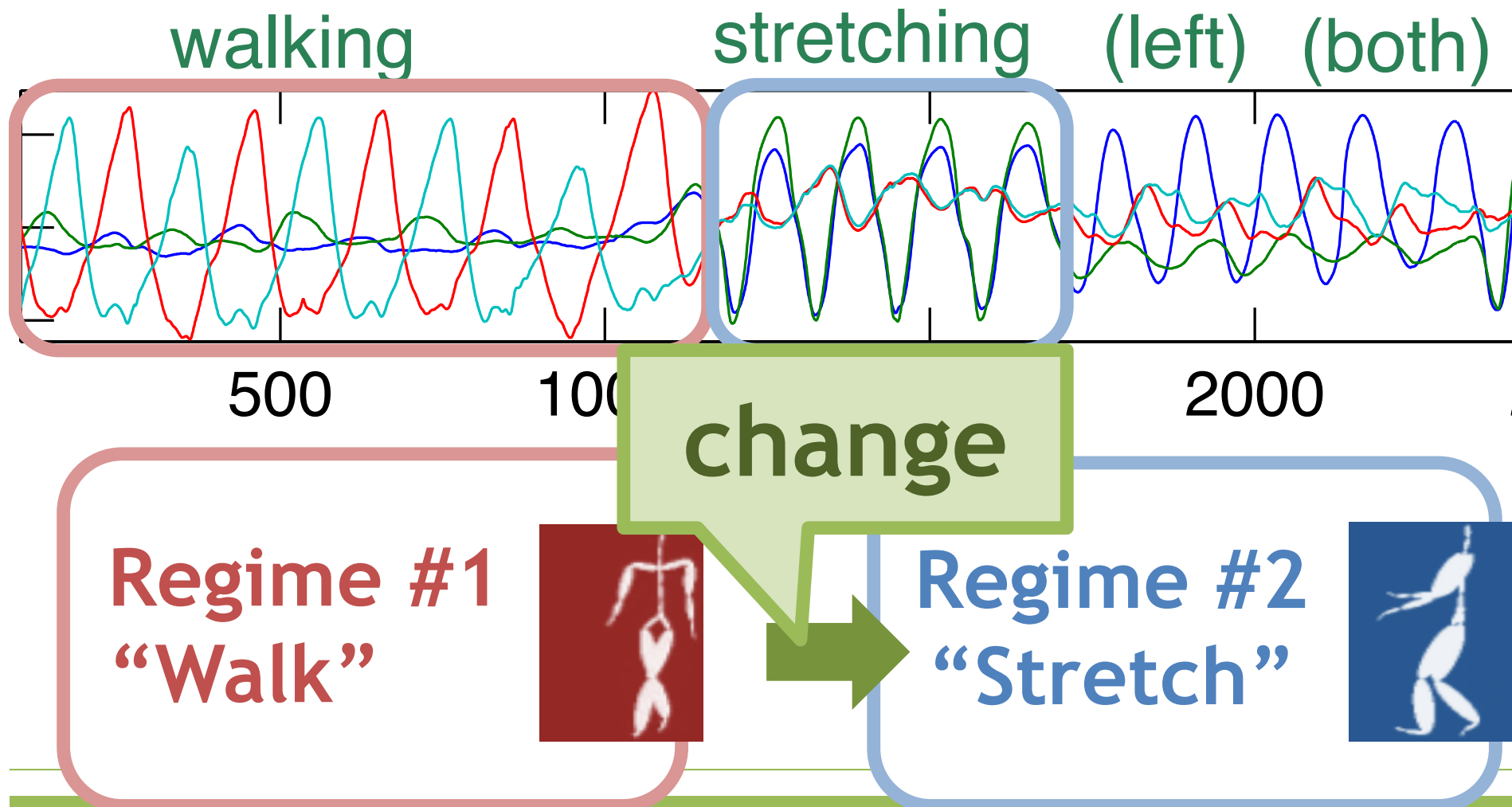
Regime #1
“Walk”



Regime shifts in streams

P2

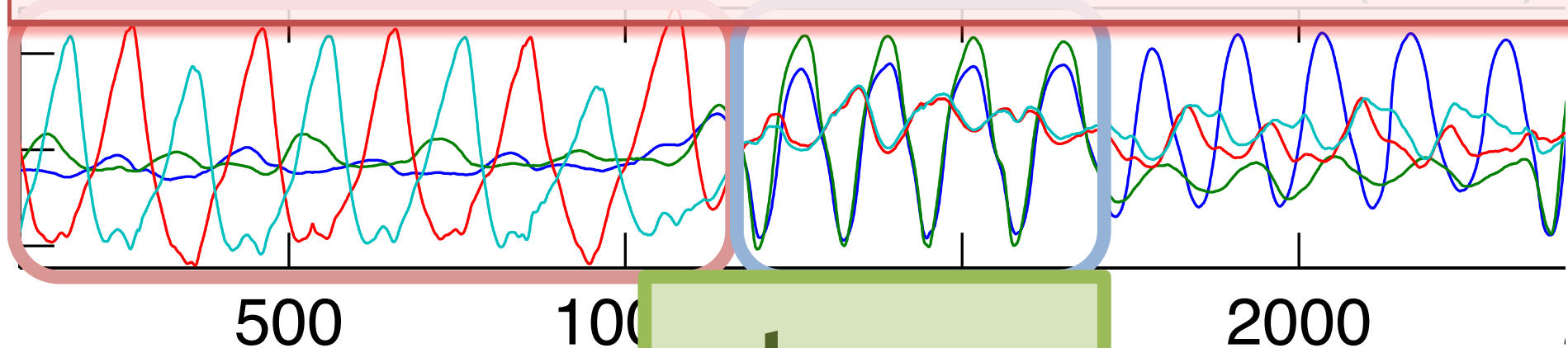
Various patterns (“**regimes**”) in streams



Regime shifts in streams

P2

Various patterns (“regimes”) in streams
walking stretching (both)
Q. How can we identify sudden discontinuities?



Regime #1
“Walk”

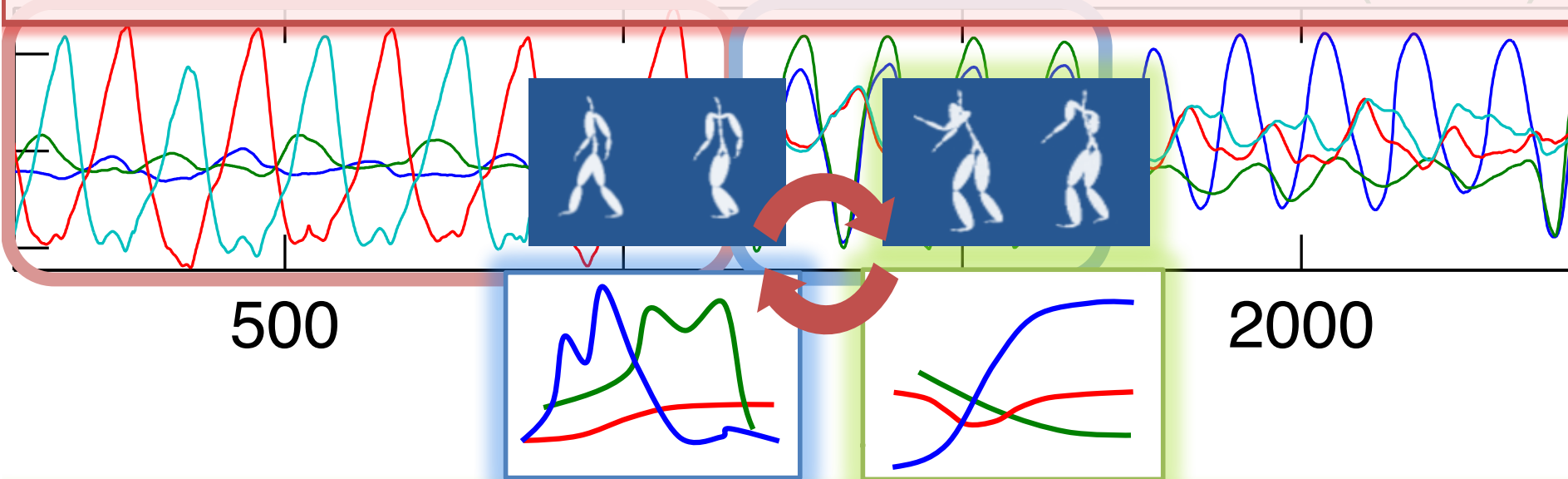


Regime #2
“Stretch”



Various patterns (“regime”) in streams
walking standing (both)

Q. How can we identify sudden discontinuities?



A: “Regime Shifts in Streams”!

Regime shifts in natural systems

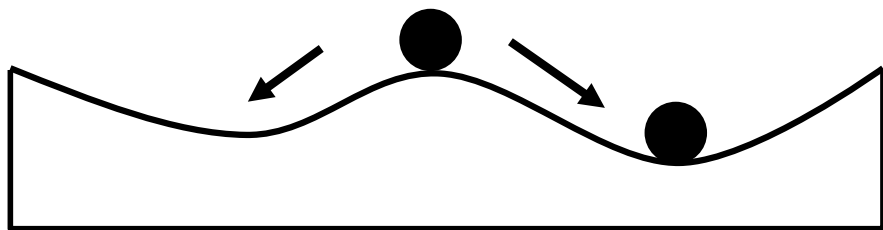
P2

Abrupt changes in the structure of complex systems



Examples:

- Woodland vs. grassland
- Coral vs. macro algae
- Desert vs. vegetation



Woodlands Grasslands

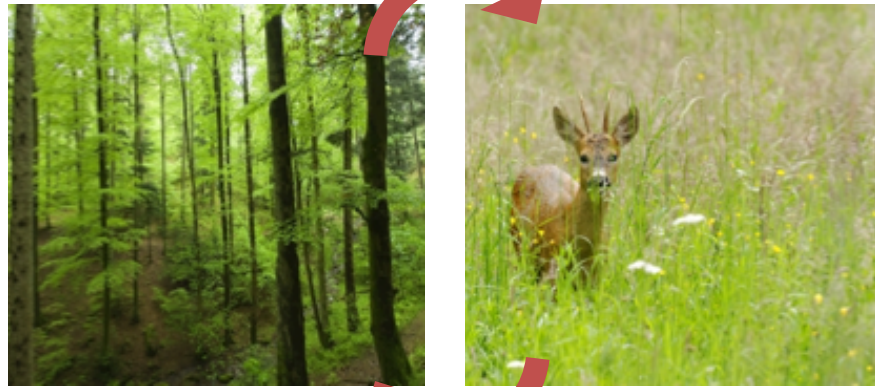
Ecological system

Regime shifts in natural systems

P2

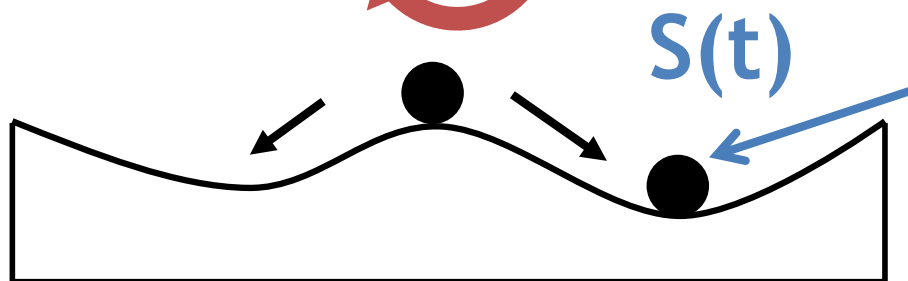
Abrupt changes in the structure of complex systems

Details



$$\frac{ds(t)}{dt} = a_0 + a_1 s(t) + a_2 f(s(t))$$

Time-evolving
ecosystem property
(nutrients/soils)



Woodlands Grasslands

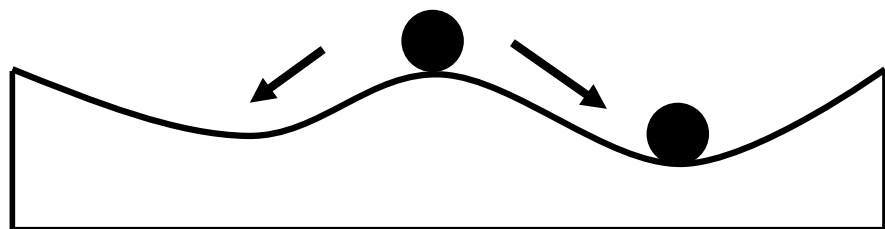
Ecological system

a_0 : environmental factor
 a_1 : growth/decay rate
 a_2 : recover rate

Regime shifts in event streams

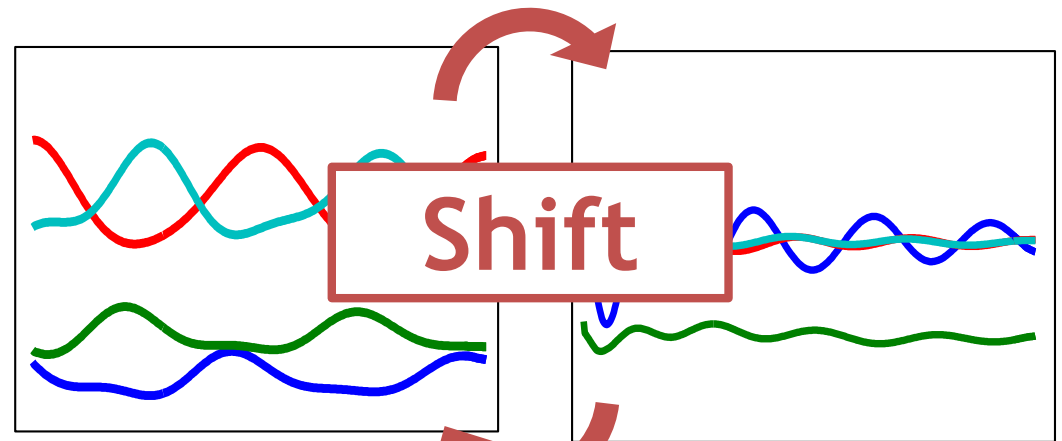
P2

Abrupt changes in the structure of complex systems



Woodlands Grasslands

Ecological system



Walking



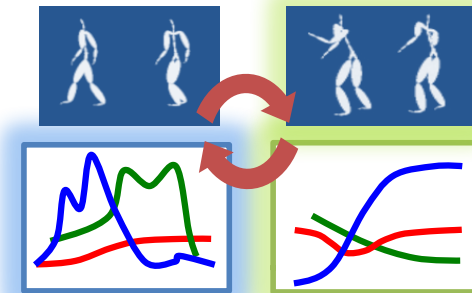
Wiping

Motion sensors

Regime shifts in event streams

P2

L-NLDS + regime activity



$$\frac{ds_i(t)}{dt} = p_i + Q_i s_i(t) + A_i S_i(t) \quad (i = 1, \dots, c)$$

Details

$$\frac{dw(t)}{dt} = r(t), \mathbf{R} = \{r(t)\}_{t=1}^{t_c}$$

$$\mathbf{v}(t) = \sum_{i=1}^c w_i(t) [\mathbf{u}_i + \mathbf{V}_i \mathbf{s}_i(t)]$$

R: Regime shift dynamics

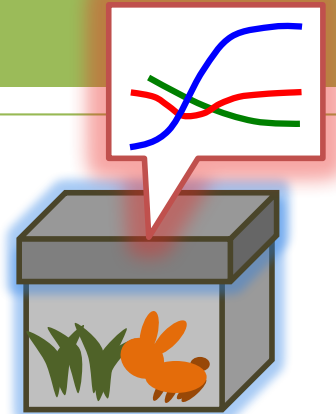
$$\Theta = \{\theta_1, \dots, \theta_c, \mathbf{R}\}$$

c: # of regimes

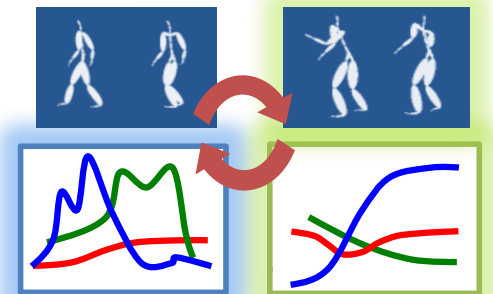
Proposed model

Main ideas

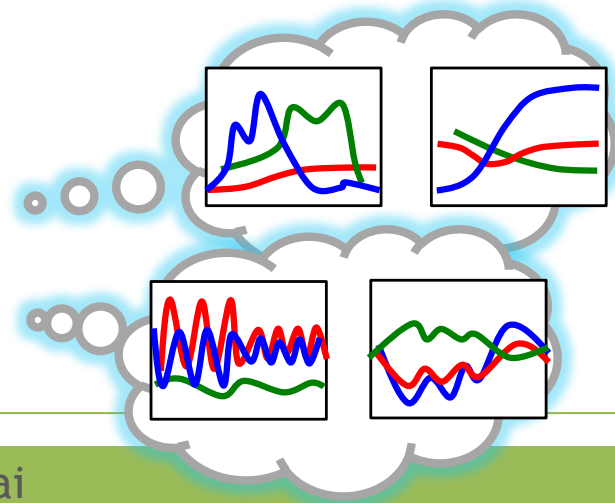
✓ **P1** Latent non-linear dynamics



✓ **P2** Regime shifts in streams



P3 Nested structure

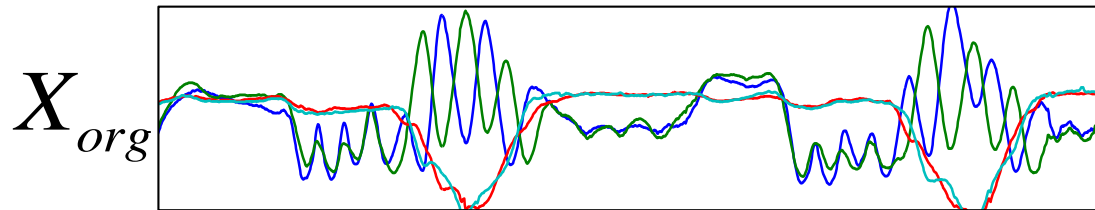


Nested, multi-scale dynamical activities

Chicken
dance



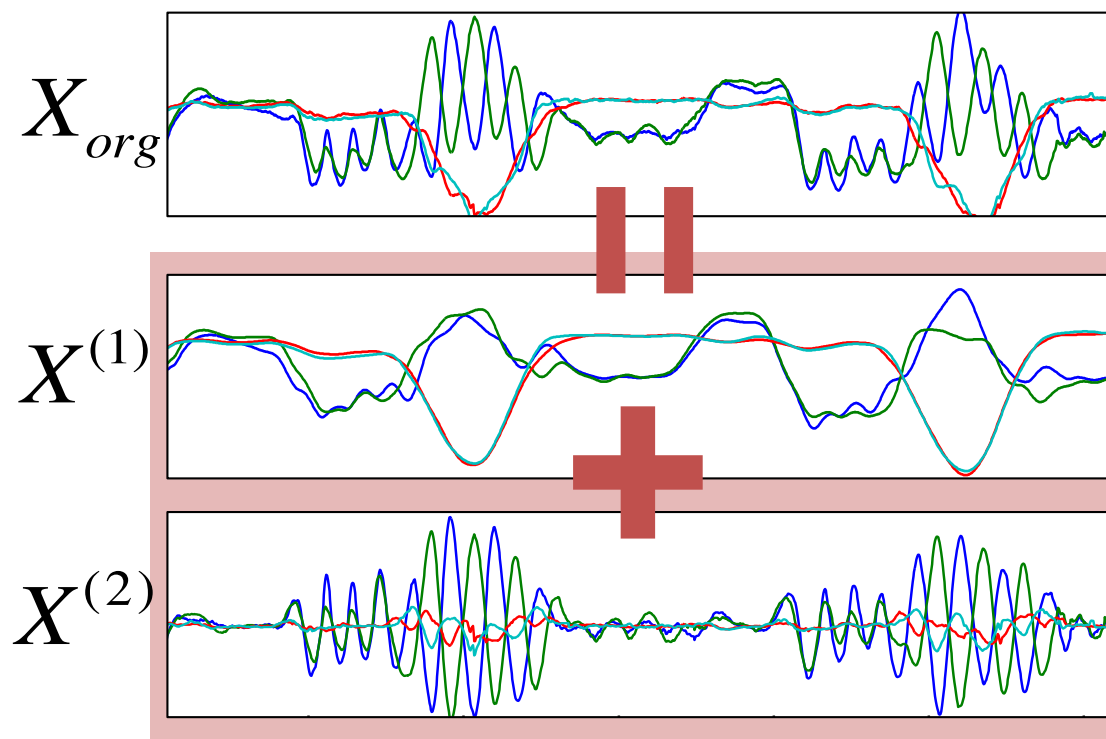
Nested, multi-scale dynamical activities



Chicken
dance



Nested, multi-scale dynamical activities



Chicken
dance

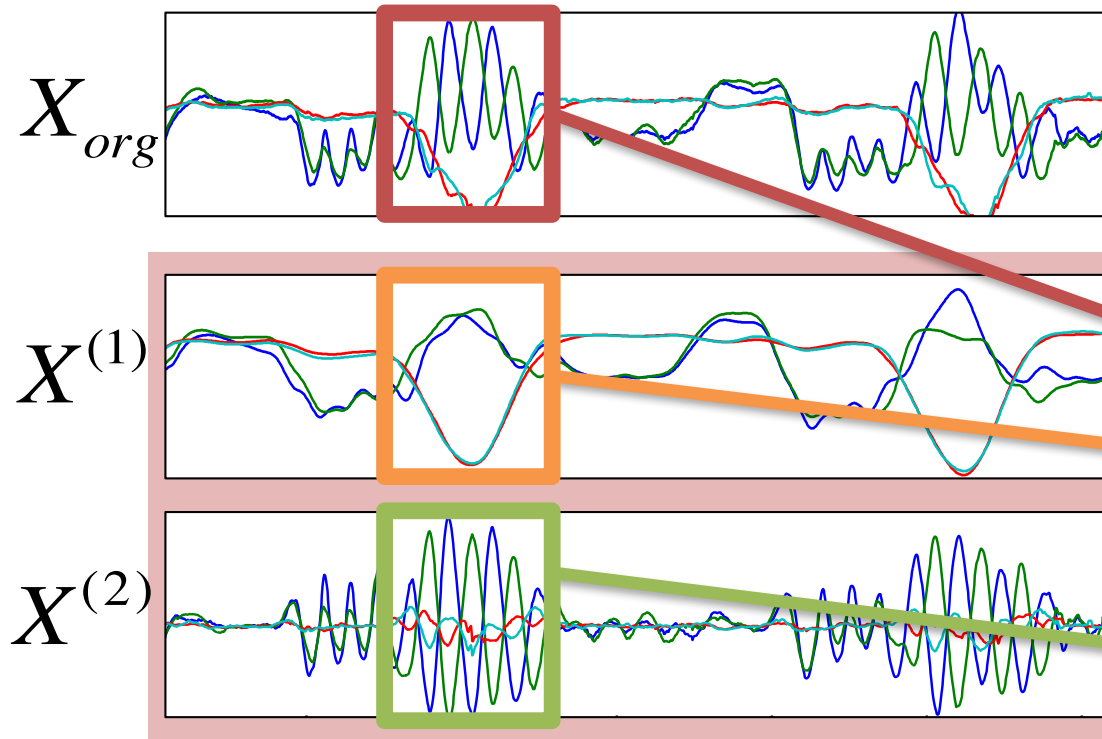
Original events

$X^{(1)}$: Long-term

+

$X^{(2)}$: Short-term

Nested, multi-scale dynamical activities



Chicken
dance

$$X_{org} = X^{(1)} + X^{(2)}$$

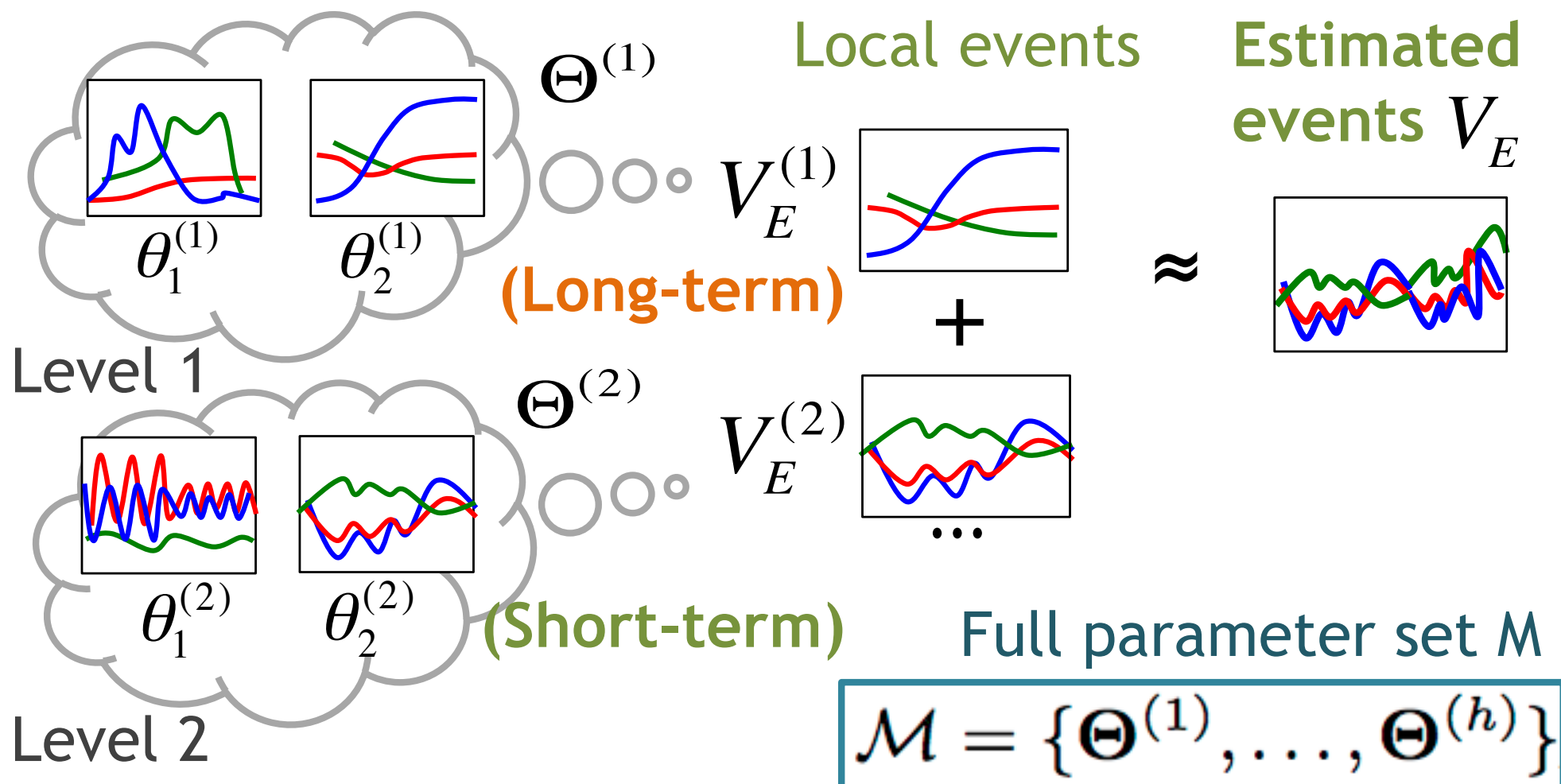
Tail feathers =
bending knees, once
+
moving arms, quickly

Nested structure

P3

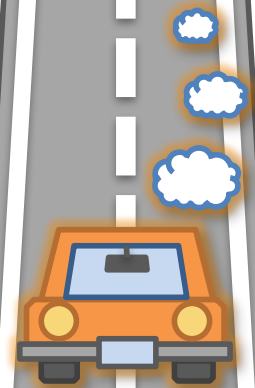
Details

Multi-level modeling structure



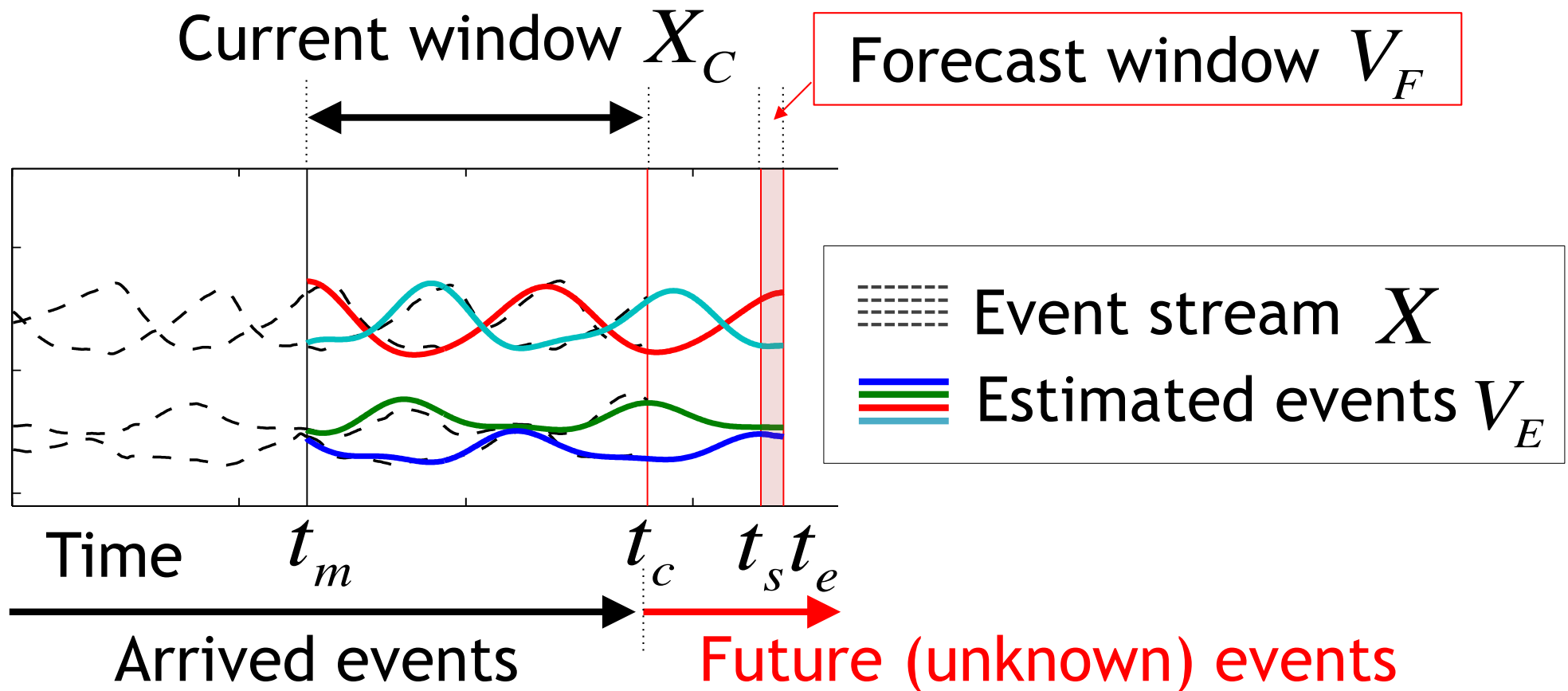
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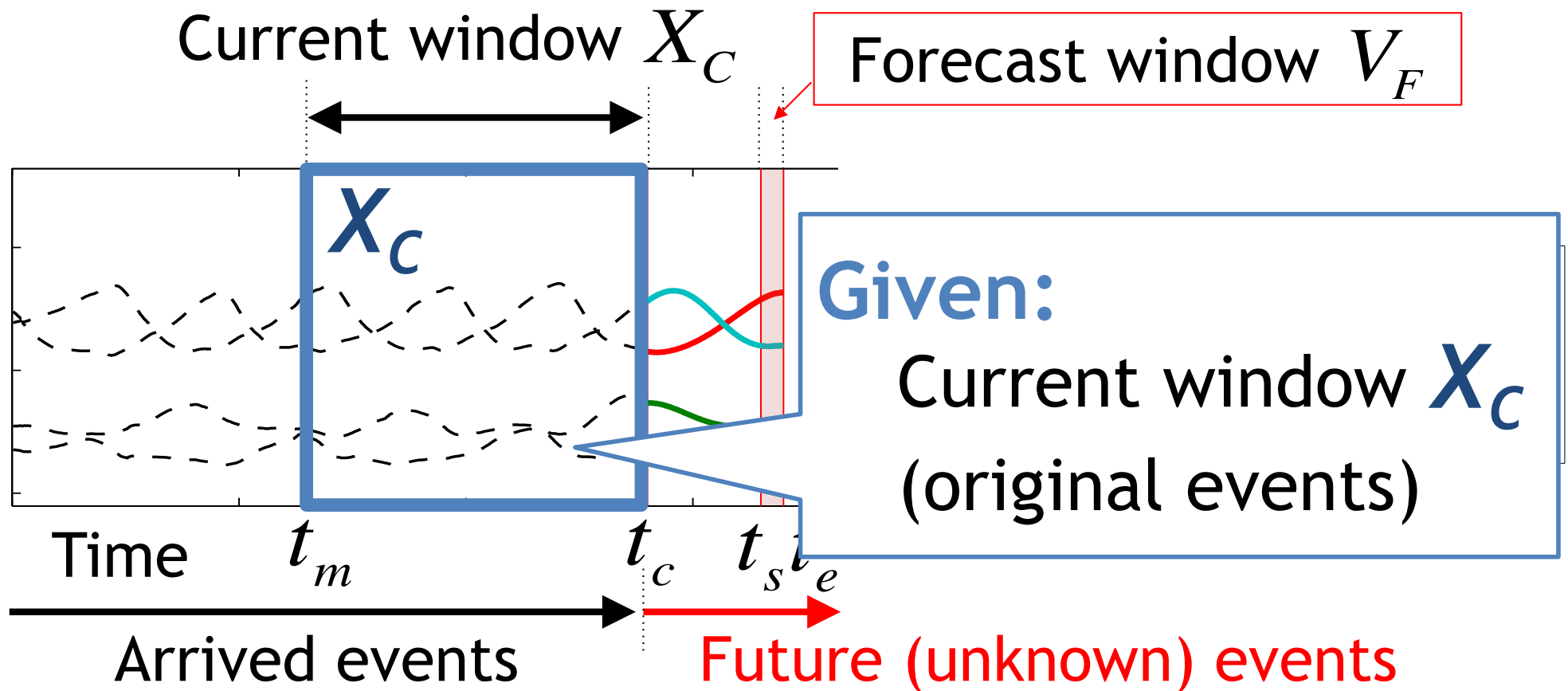
Problem definition

- RegimeSnap



Problem definition

- RegimeSnap

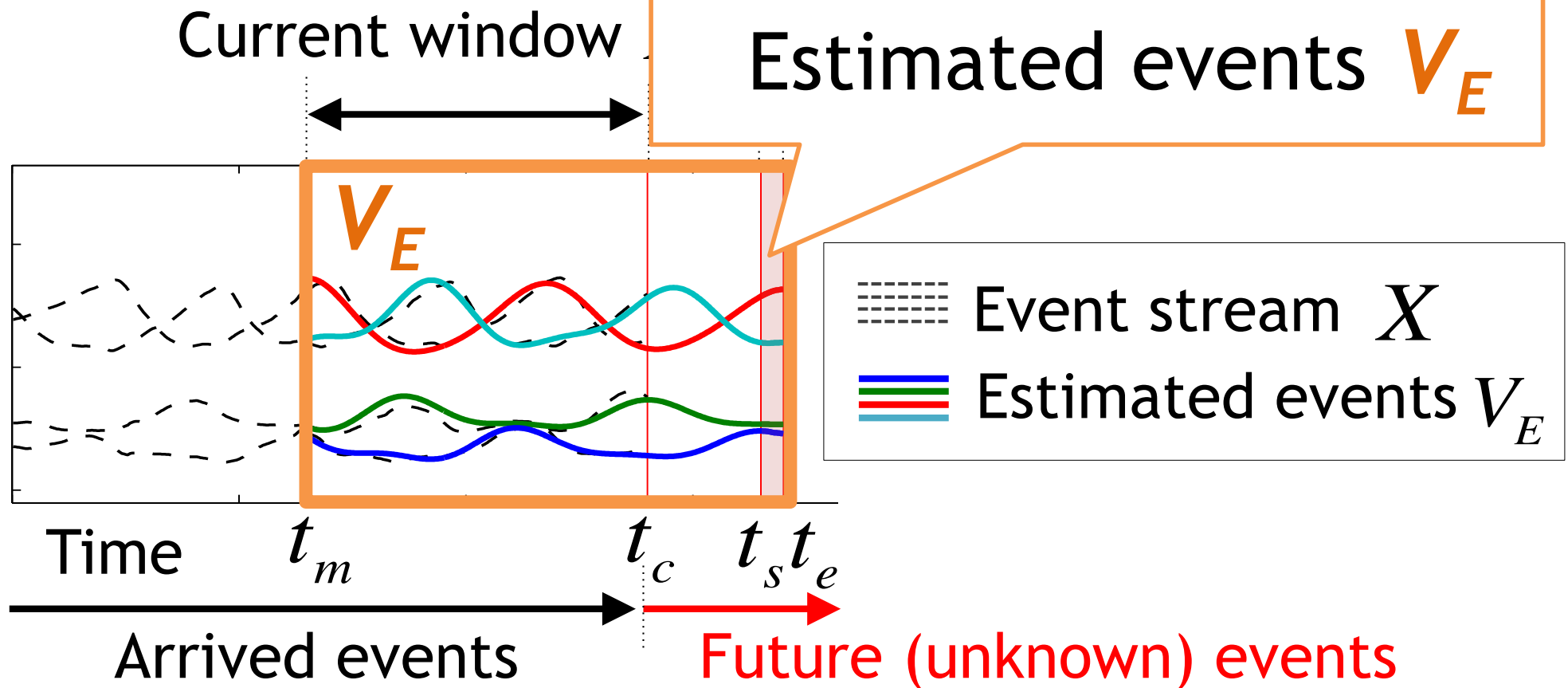


Problem definition

- RegimeSnap

Find:

Estimated events V_E

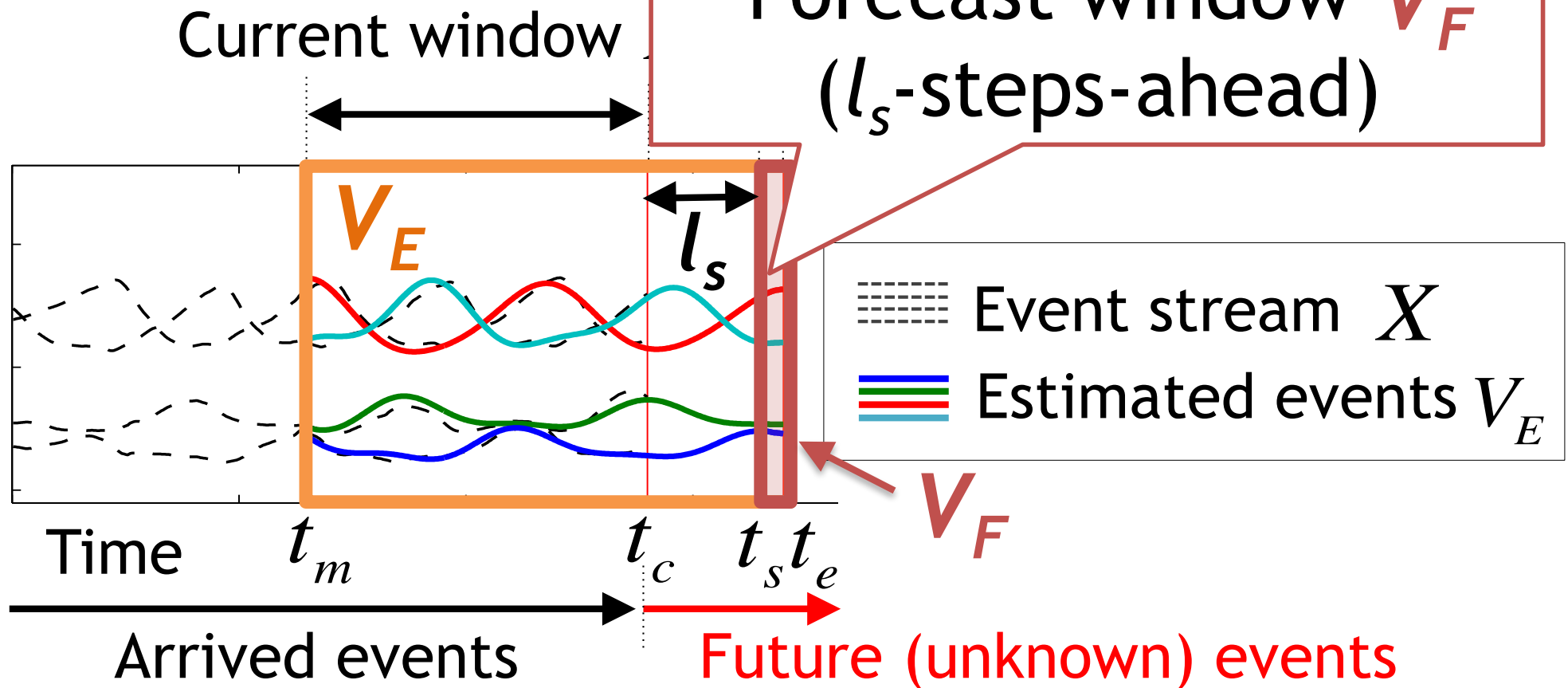


Problem definition

- RegimeSnap

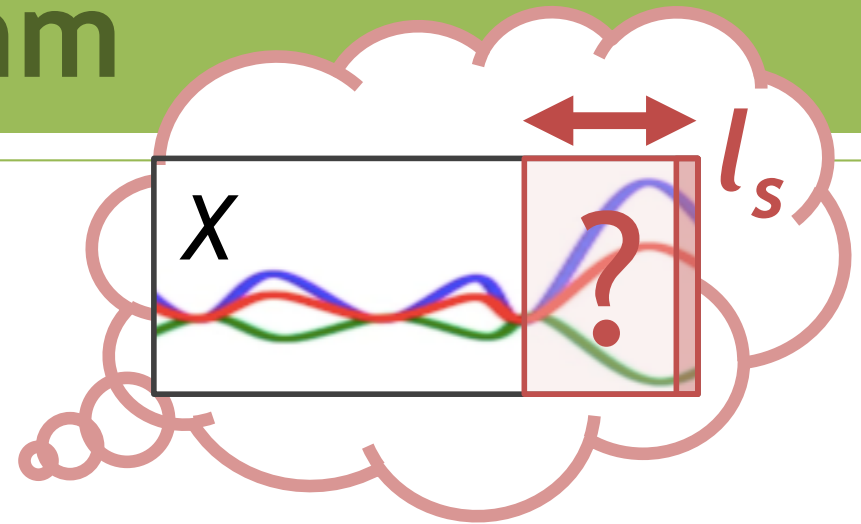
Report:

Forecast window V_F
(l_s -steps-ahead)



Streaming algorithm

- Proposed algorithms



A1

RegimeCast

Report l_s -steps-ahead future events

A2

RegimeReader

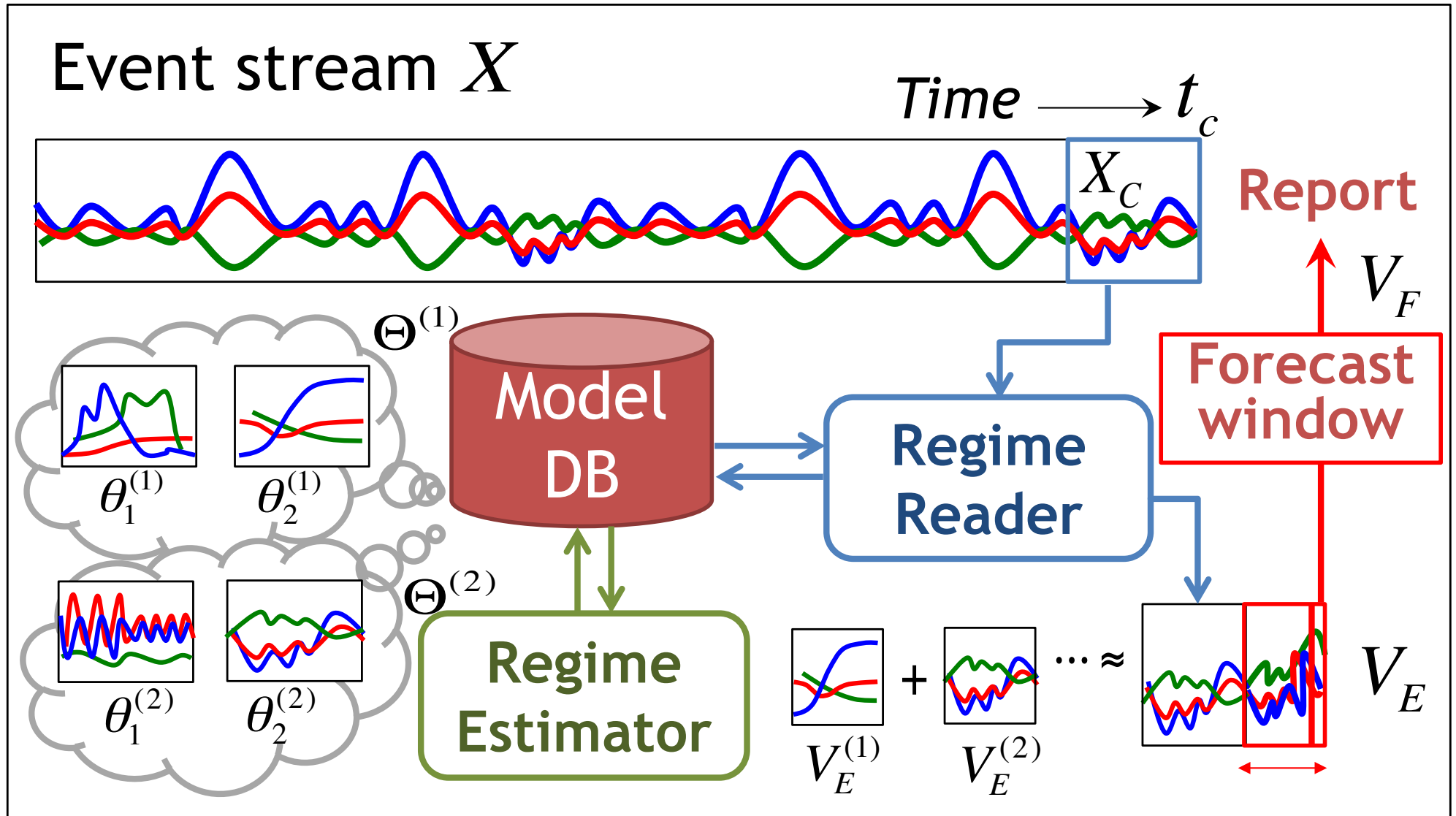
Identify current regime dynamics

A3

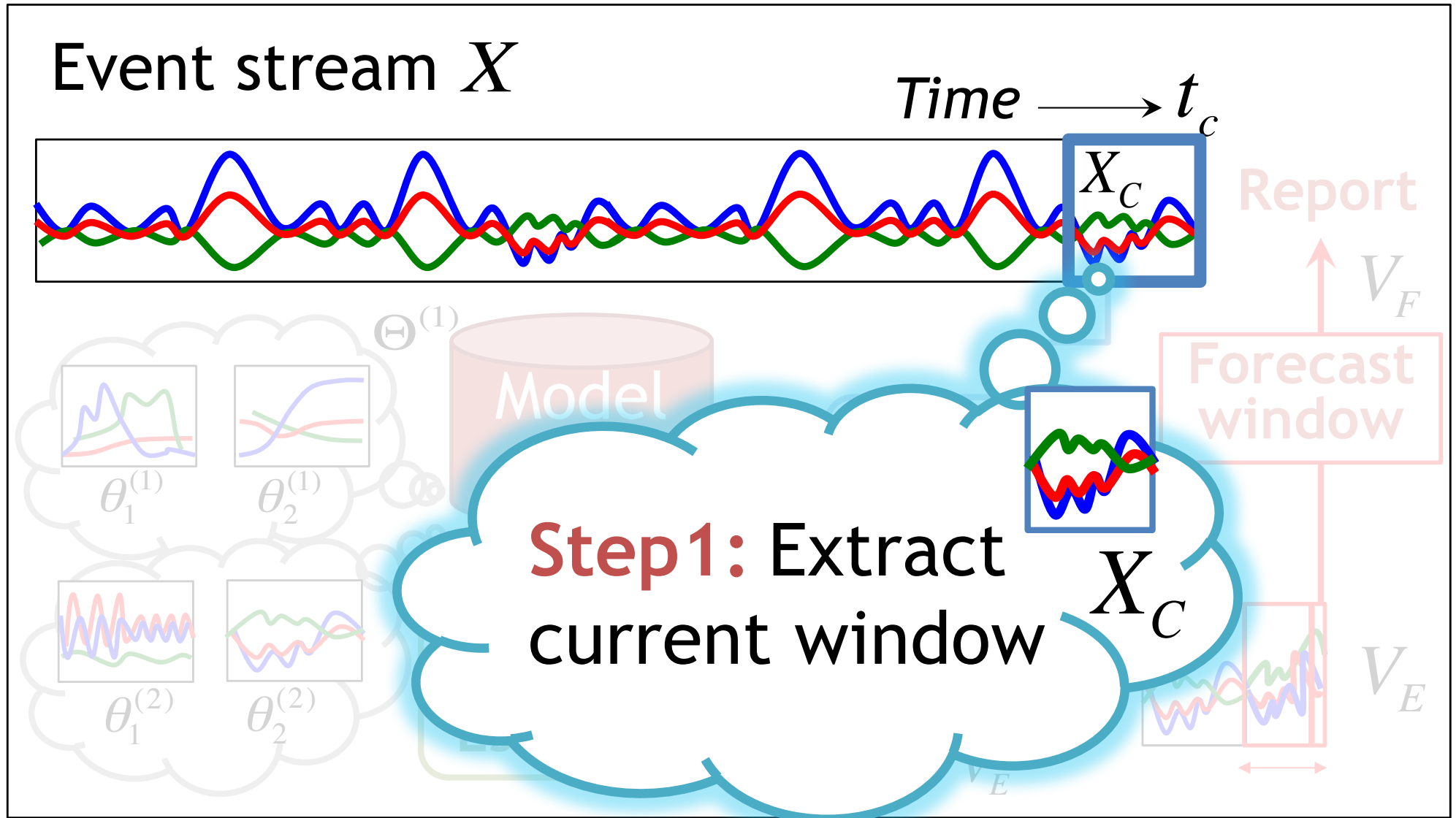
RegimeEstimator

Estimates regime parameter set θ

RegimeCast

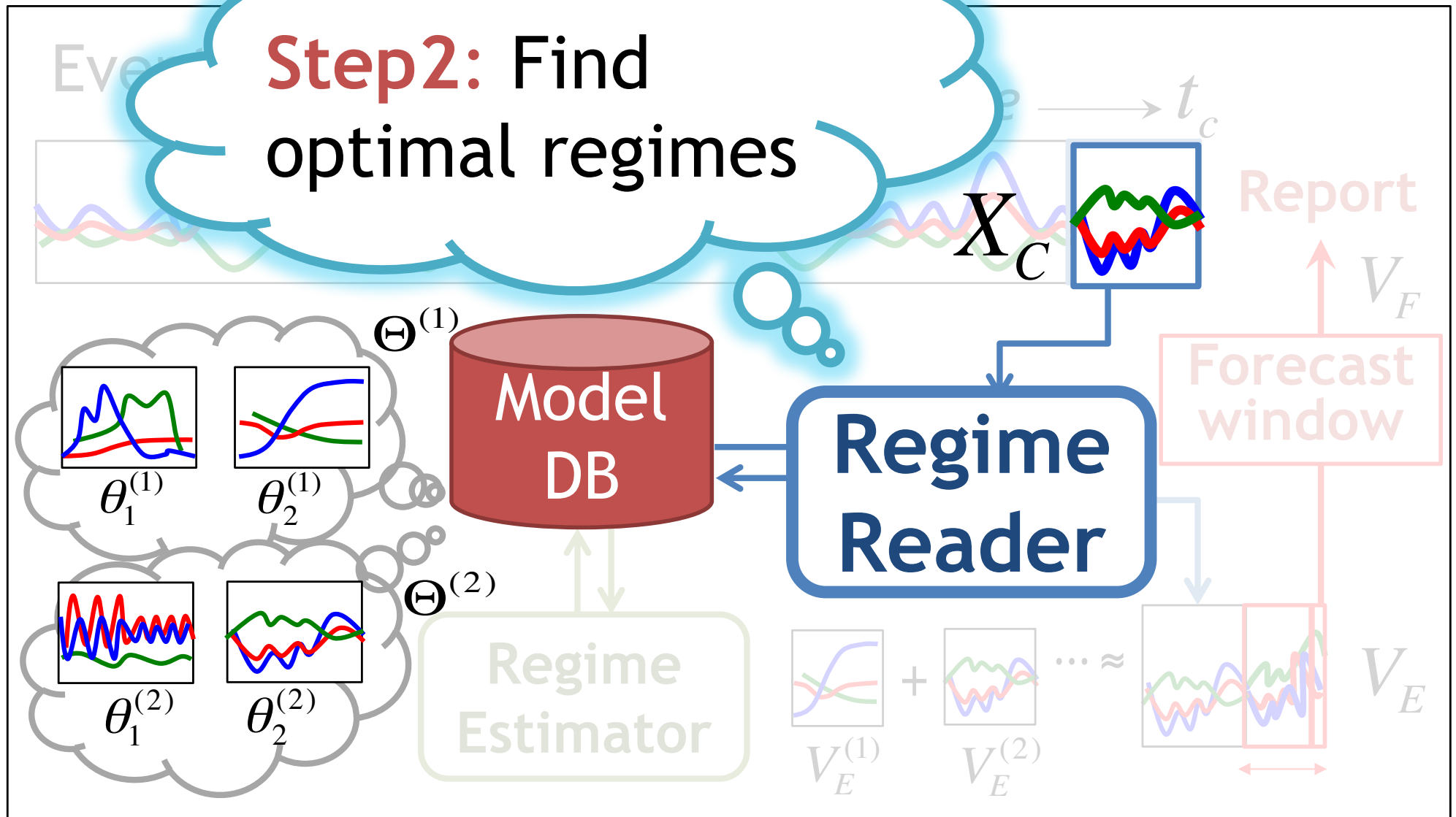


RegimeCast



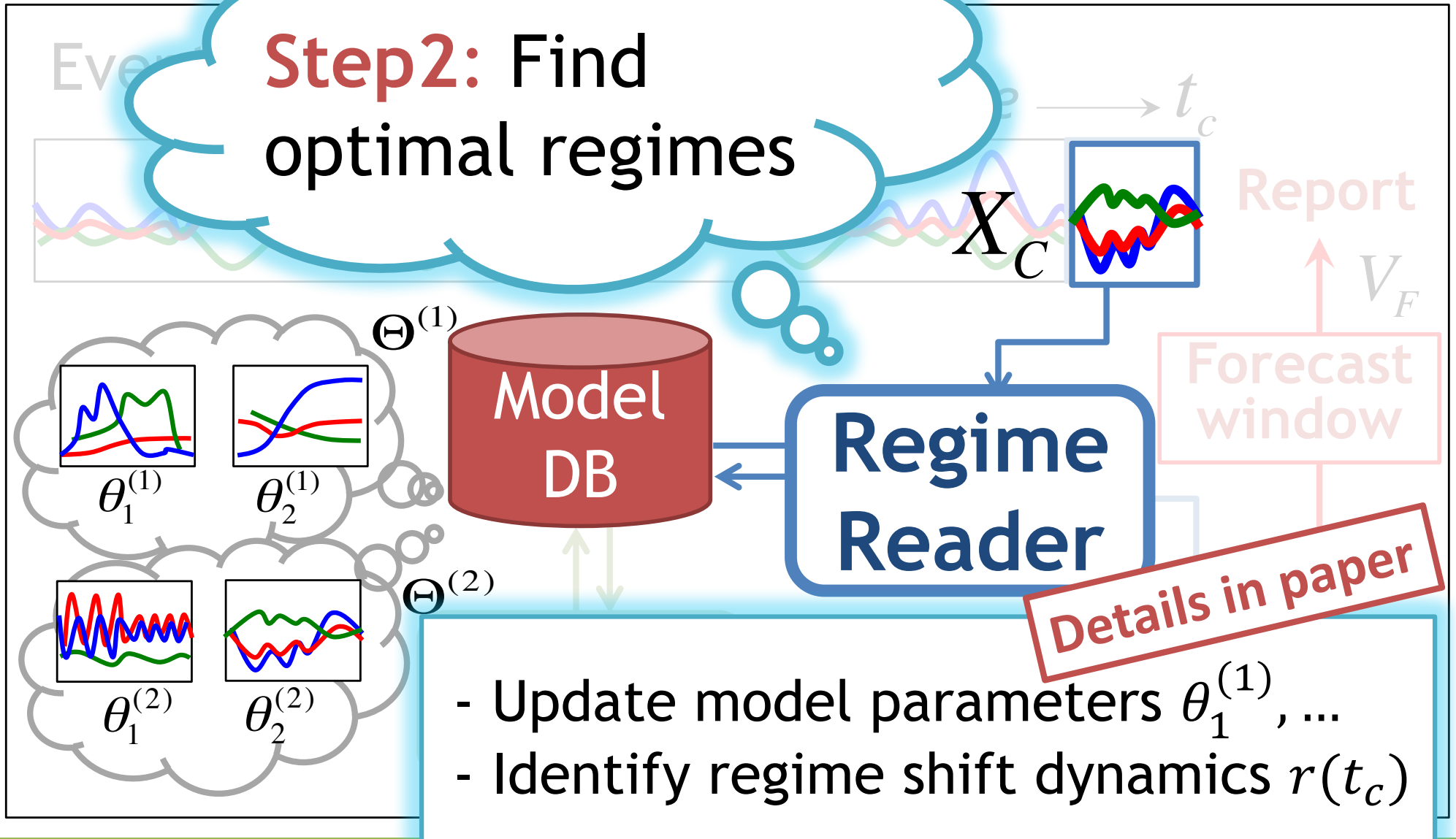
RegimeCast

Step2: Find optimal regimes



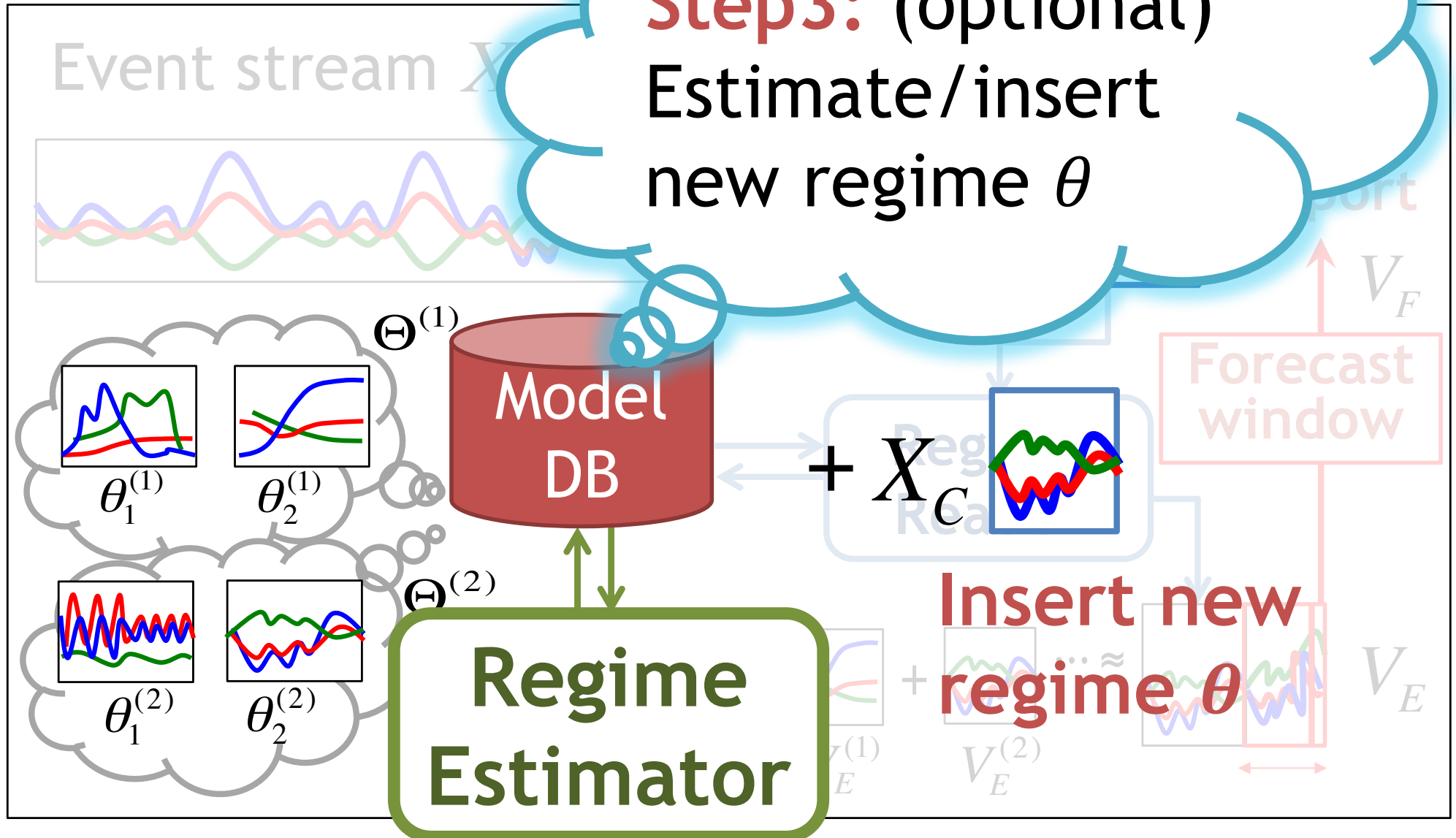
RegimeCast

Step2: Find optimal regimes

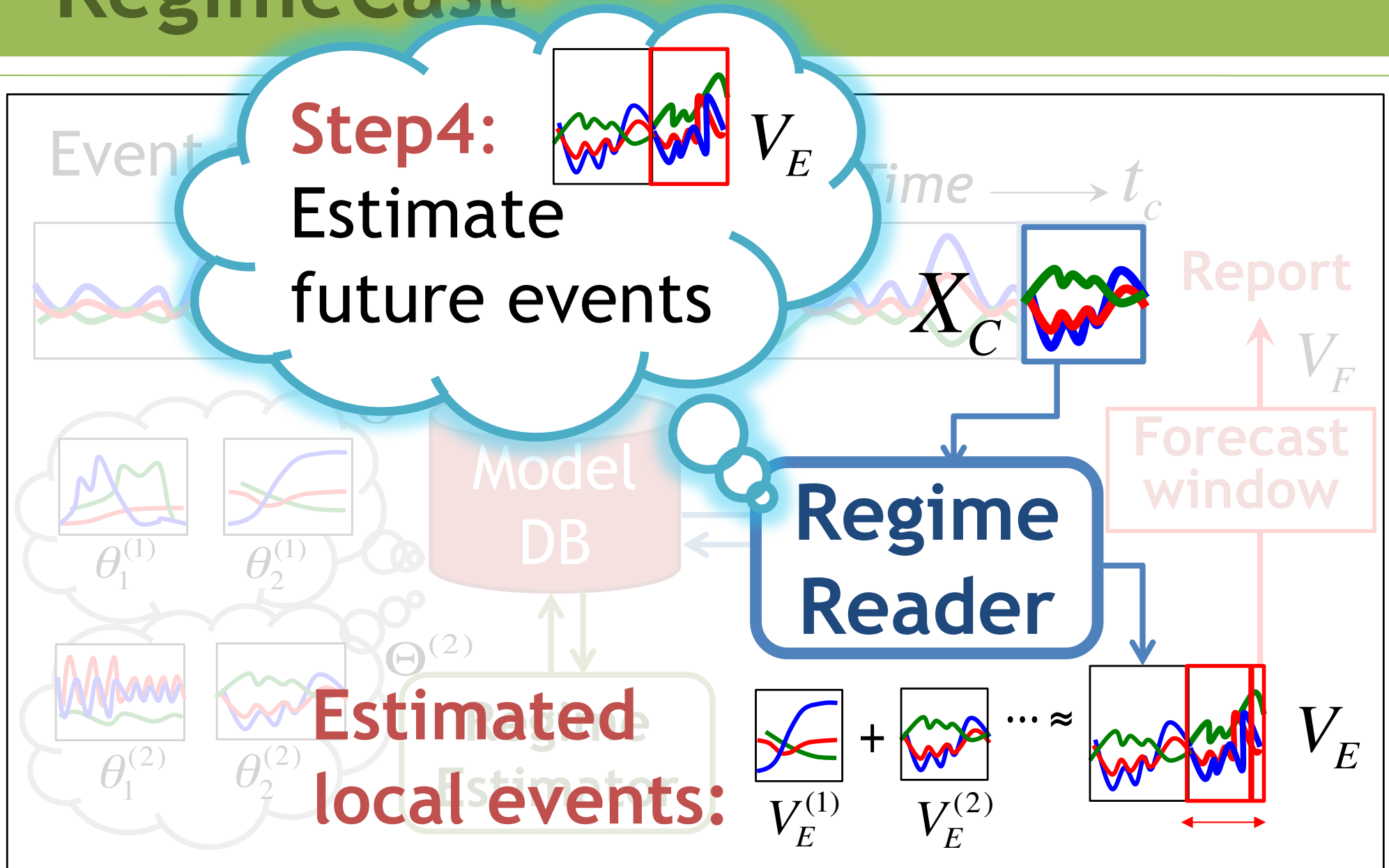


RegimeCast

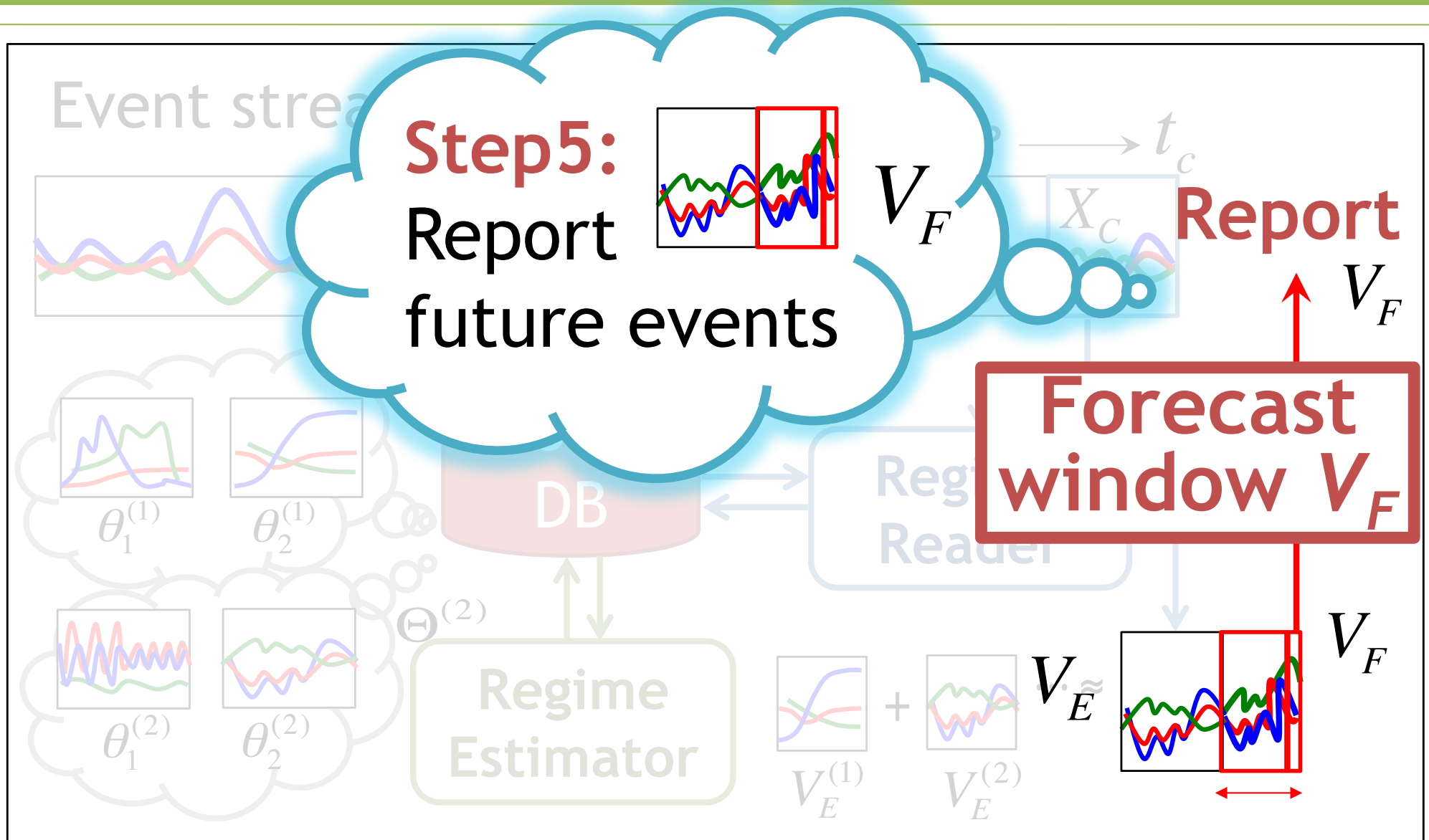
Step3: (optional)
Estimate/insert
new regime θ



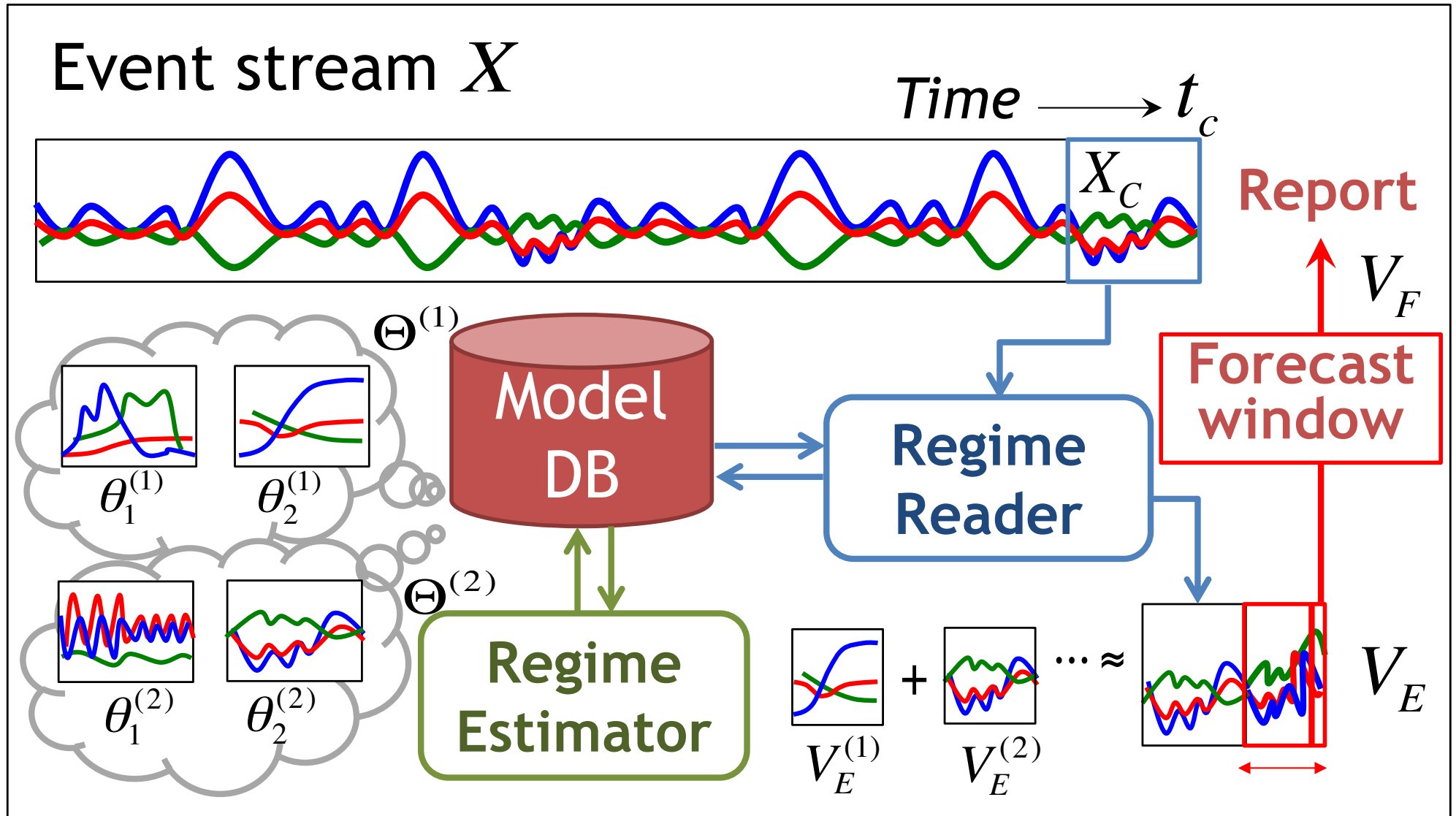
RegimeCast



RegimeCast



RegimeCast



Efficient event generation

Details

Q. How can we efficiently generate events?

A. **Dynamic point set (DPS)**

Scalability (RegimeCast)

at least $O(c \cdot l_e / \delta)$ at most $O(c \cdot l_e / \delta + l_c)$

- c : # of regimes
- l_e : Length of V_E
- δ : DPS interval
- l_c : Length of X_C

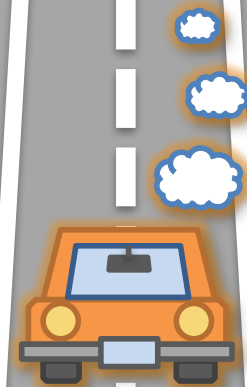
(if there's a new regime in X_C)

Details in paper

* It does not depend on data length t_c

Roadmap

- ✓ Motivation
- ✓ Forecasting power of RegimeCast
- ✓ Overview
- ✓ Proposed model
- ✓ Streaming algorithm
- Experiments
- Conclusions



Experiments

We answer the following questions...

Q1. Effectiveness

How successful is it in forecasting events?

Q2. Accuracy

How well does it forecast future events?

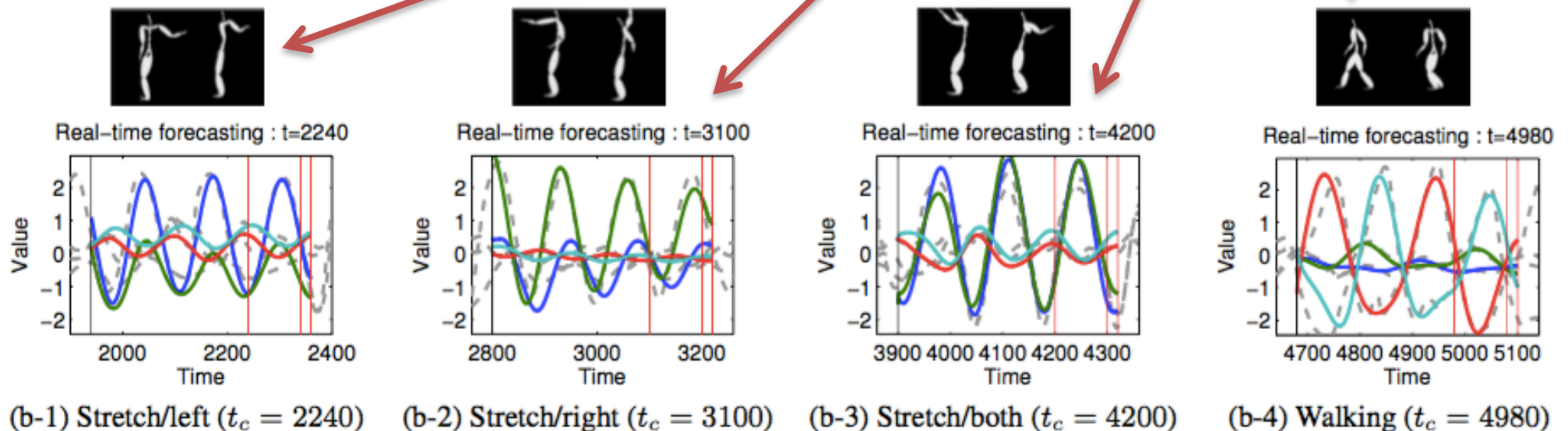
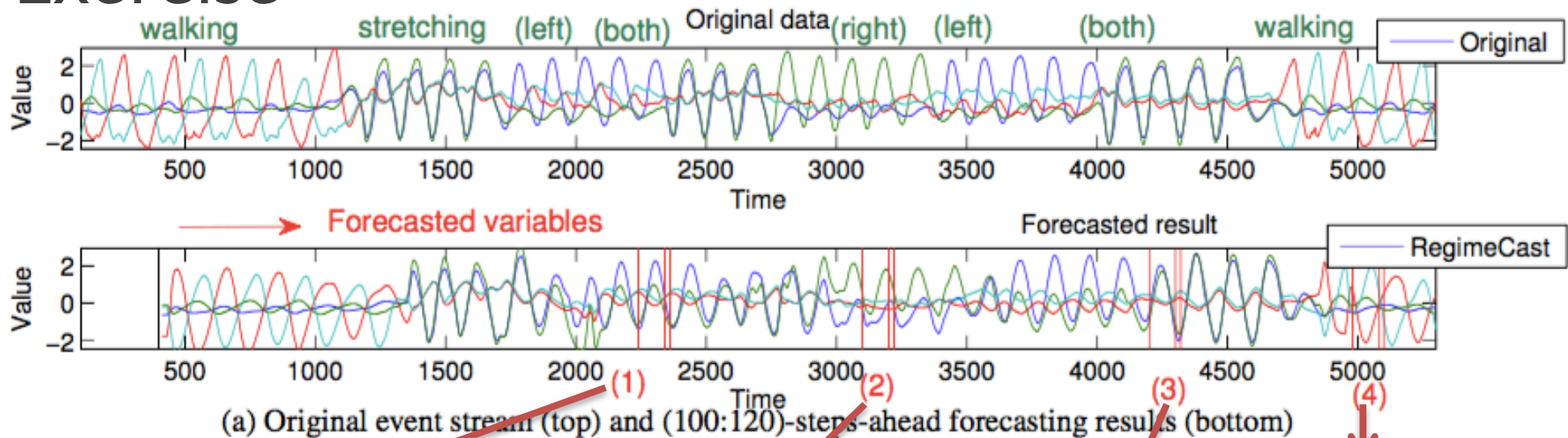
Q3. Scalability

How does it scale in terms of computational time?

Q1. Effective - MoCap #1

(100-120)-
steps ahead

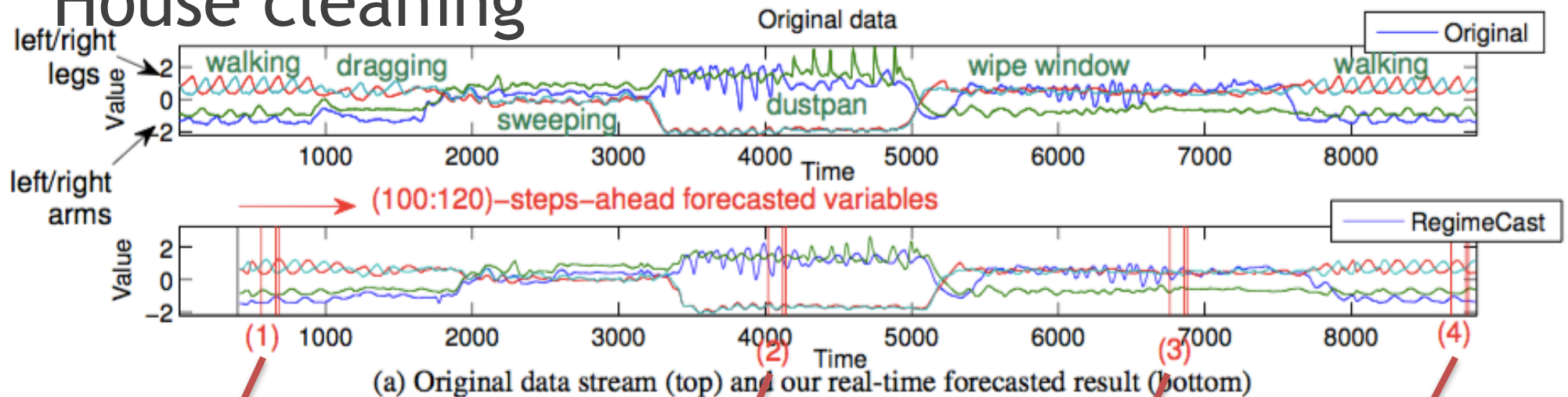
“Exercise”



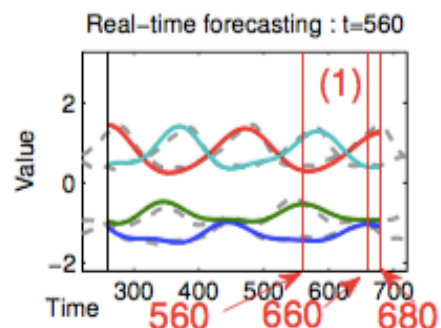
Q1. Effective - MoCap #2

(100-120)-
steps ahead

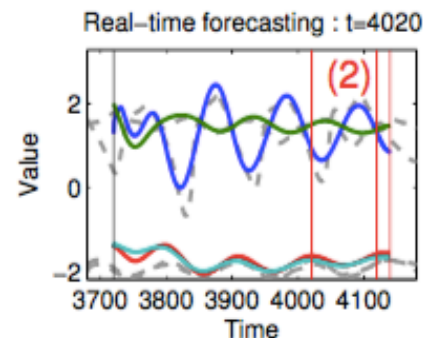
“House cleaning”



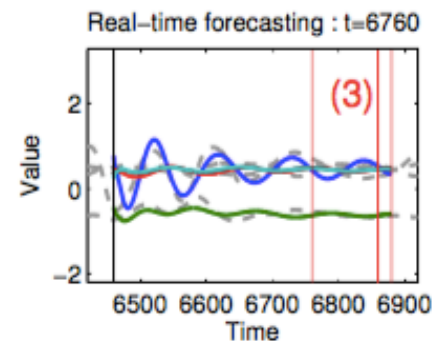
(a) Original data stream (top) and our real-time forecasted result (bottom)



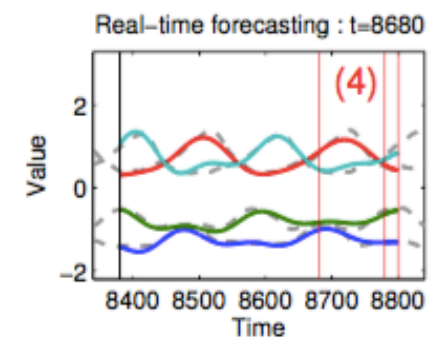
(b-1) Walking ($t_c = 560$)



(b-2) Dustpan ($t_c = 4020$)



(b-3) Wipe a window ($t_c = 6760$)

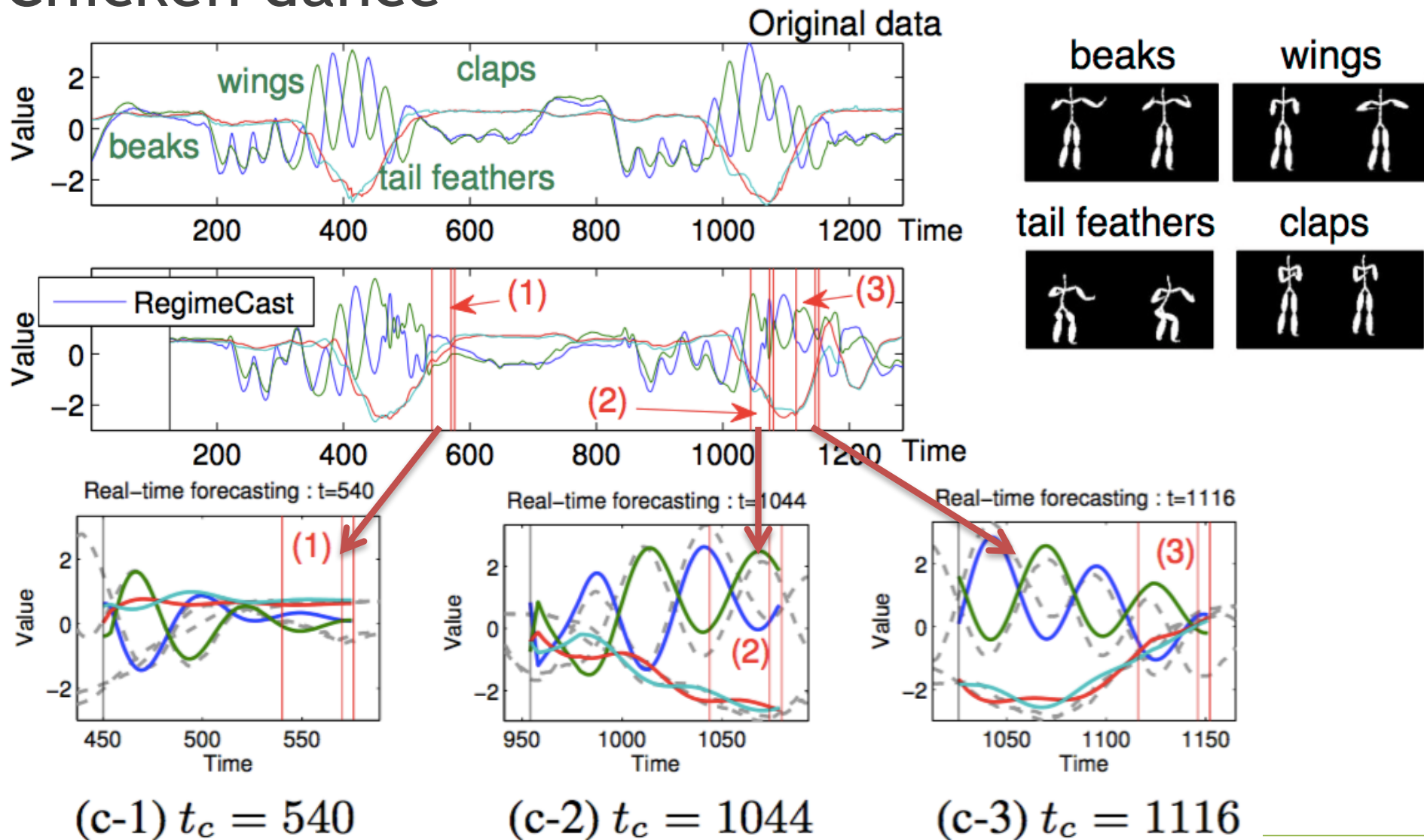


(b-4) Walking ($t_c = 8680$)

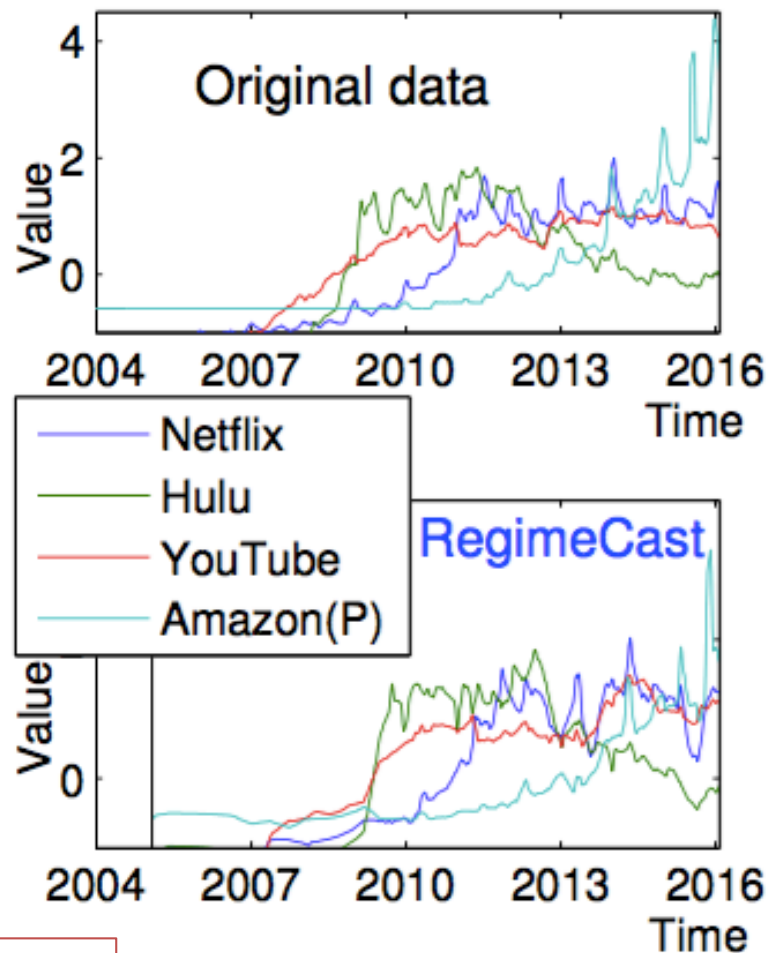
Q1. Effective - MoCap #3

(30-35)-
steps ahead

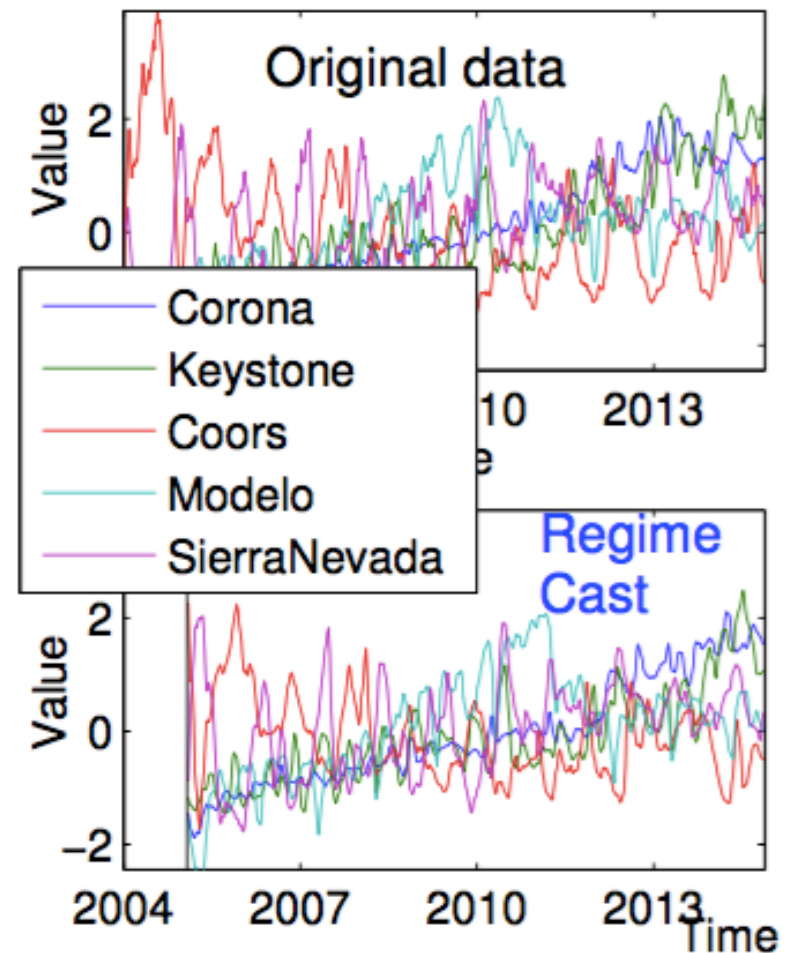
“Chicken dance”



Q1. Effective - Google Trend



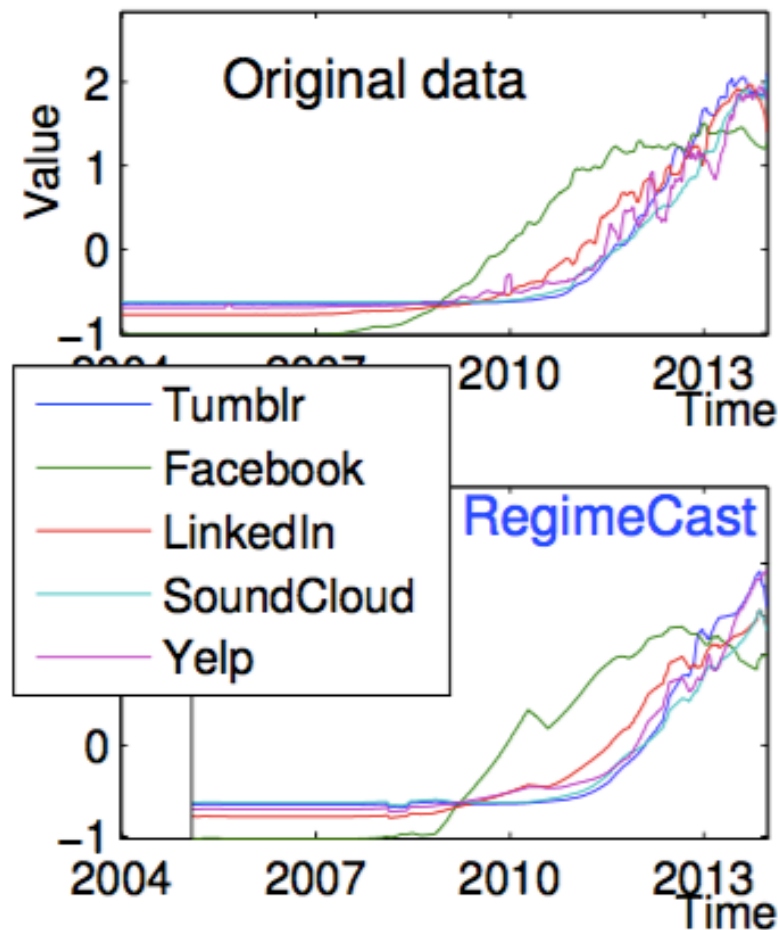
(a) Online TV



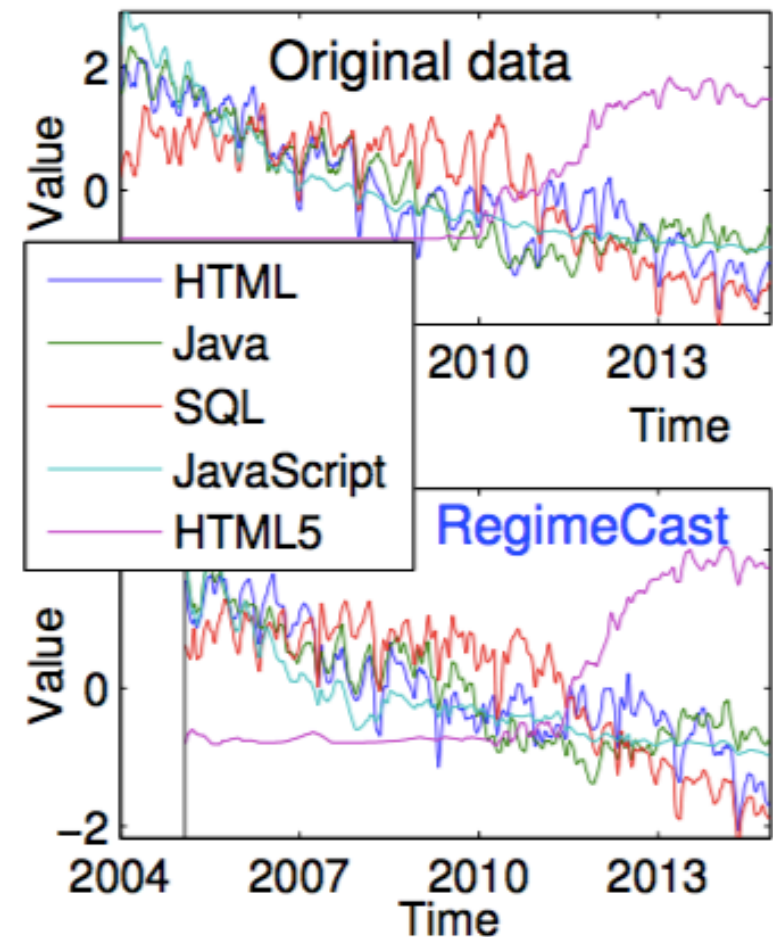
(b) Beers

**3-months
ahead**

Q1. Effective - Google Trend



(c) Social media

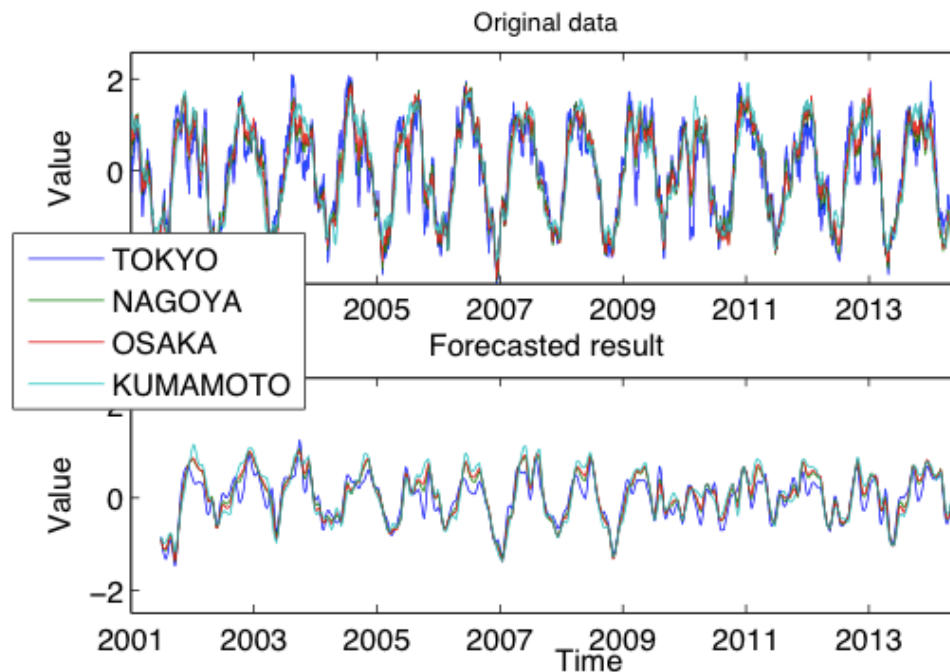


(d) Software

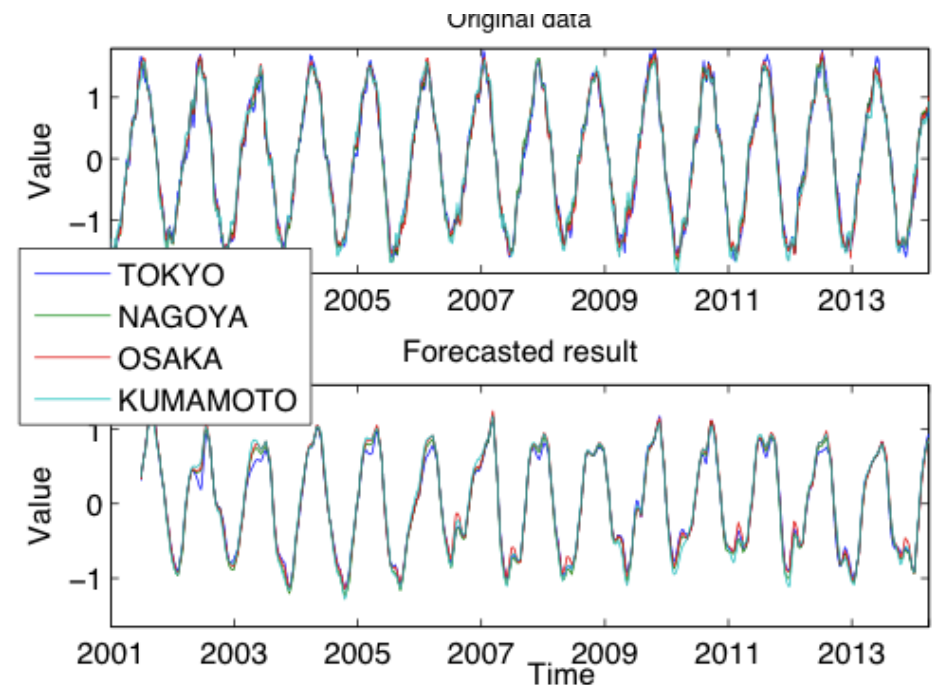
**3-months
ahead**

Q1. Effective - others

Atmospheric pressure & temperature



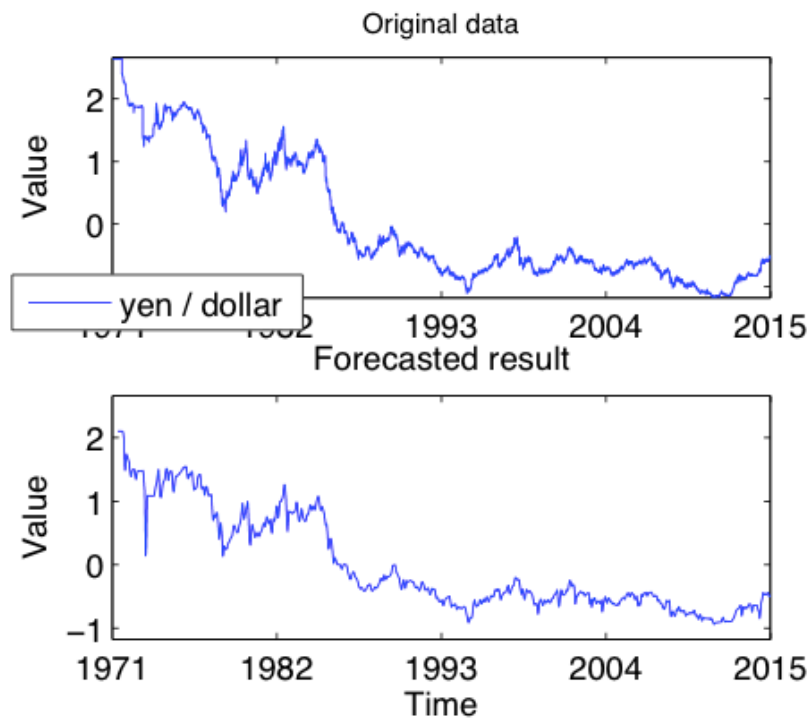
**3-months
ahead**



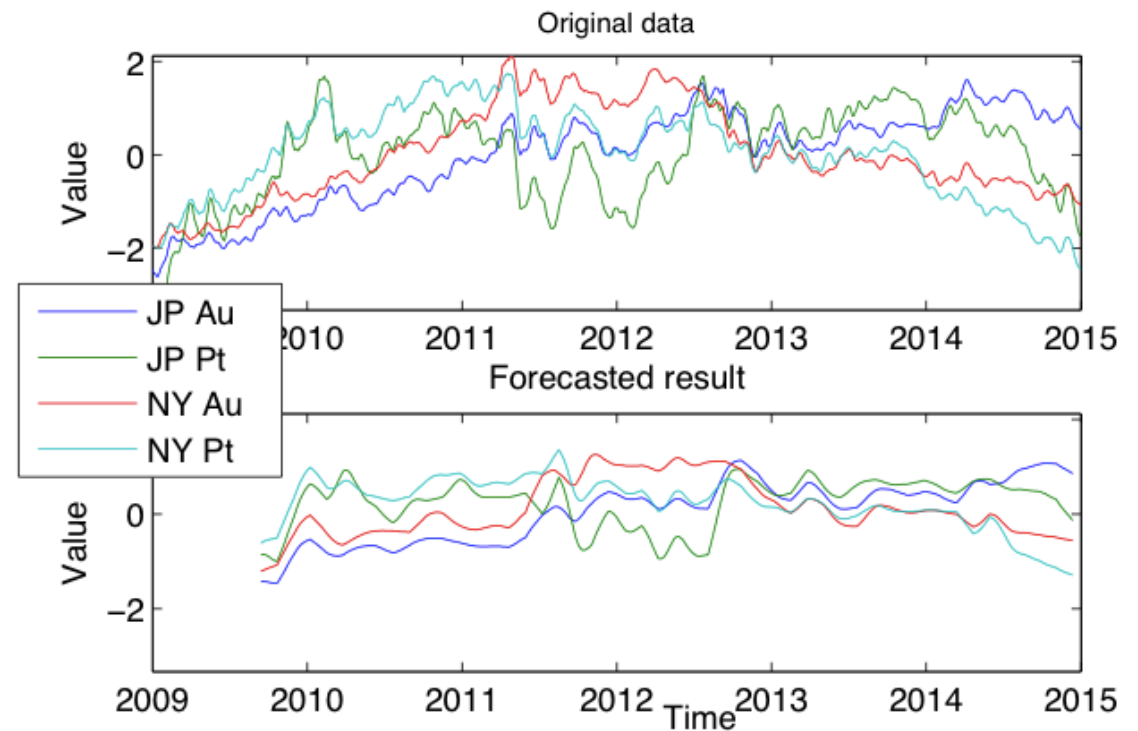
**3-months
ahead**

Q1. Effective - others

Yen vs. dollar & AU vs. PT



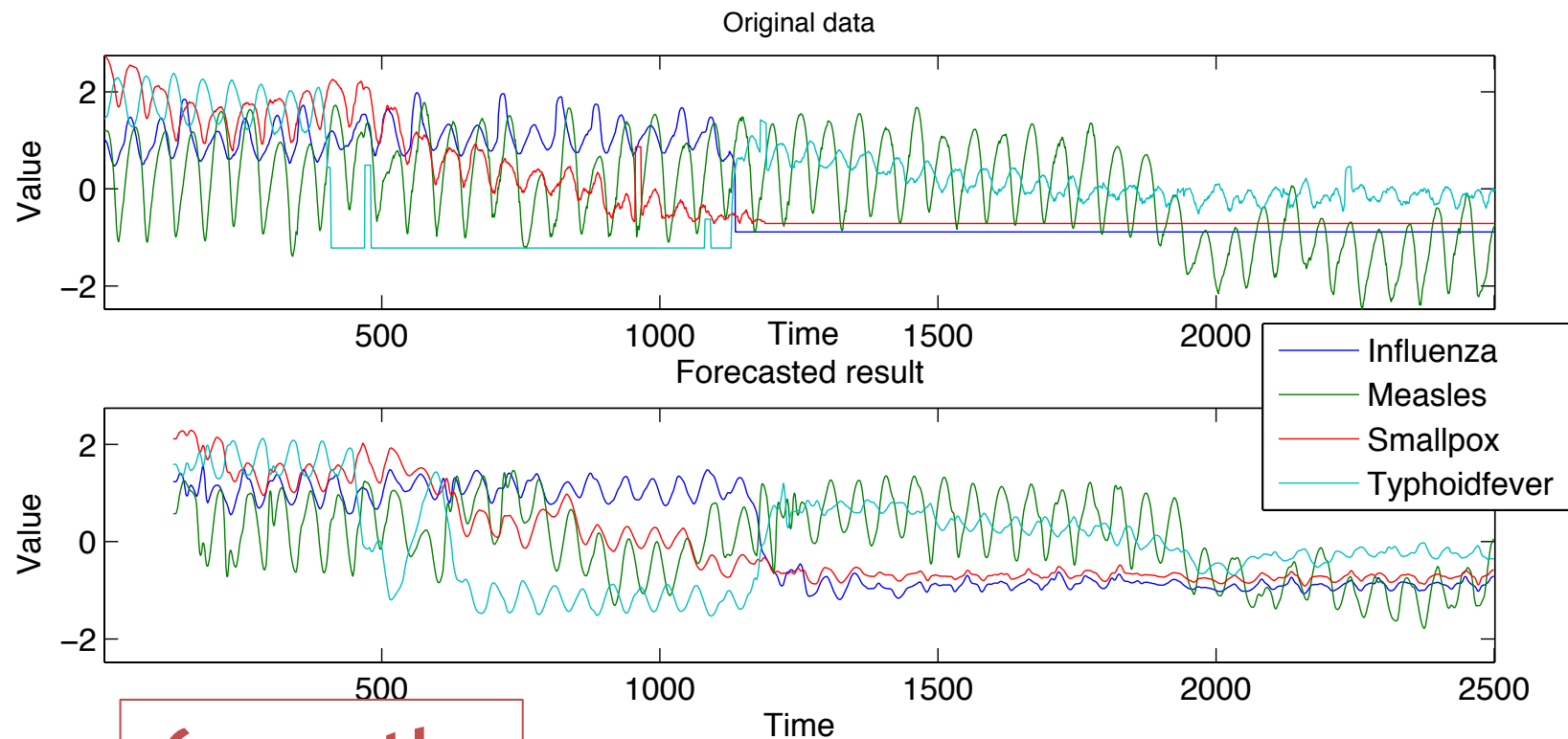
**6-weeks
ahead**



**3-months
ahead**

Q1. Effective - others

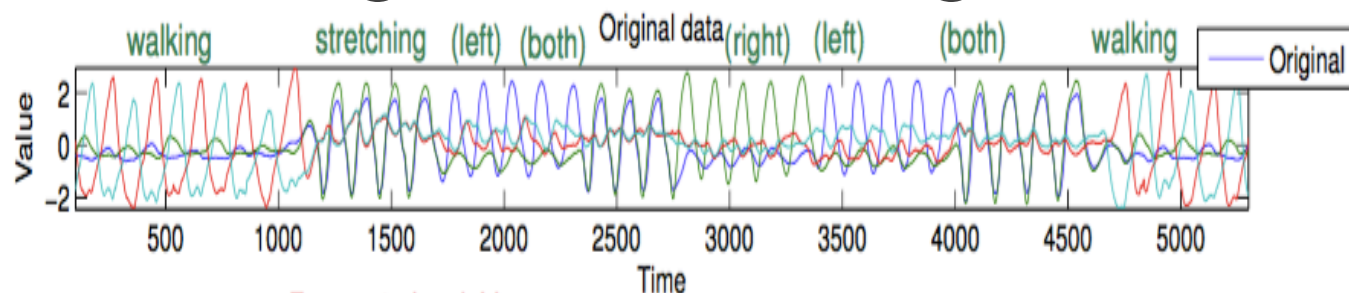
Epidemic data (1930-1978)



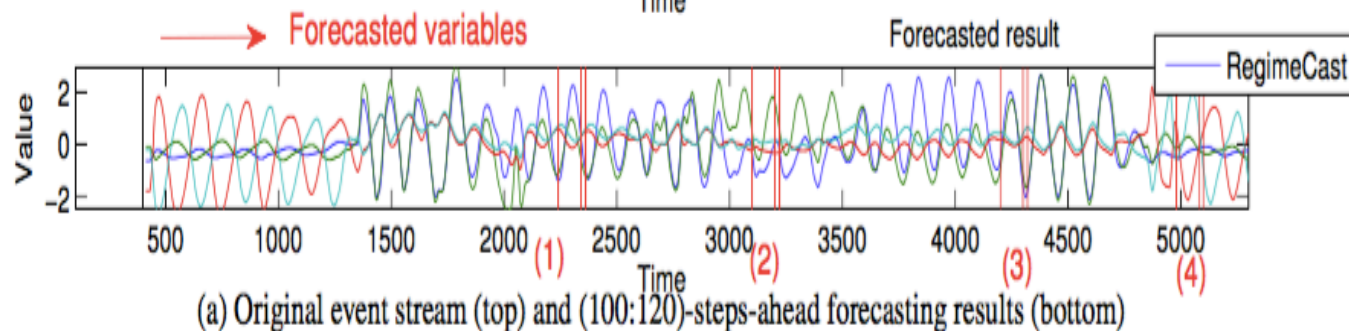
X(1000:3500)

Q2. Accuracy

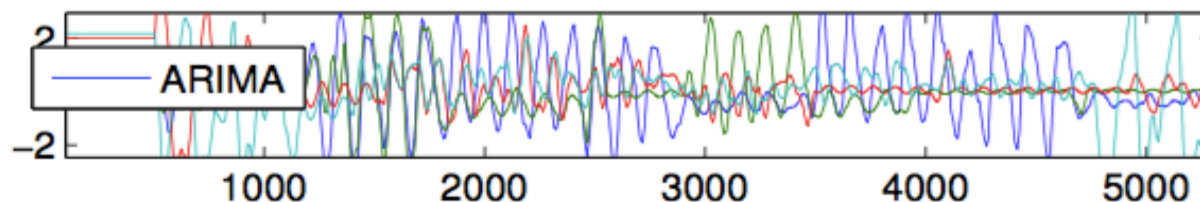
Forecasting results of RegimeCast vs. others



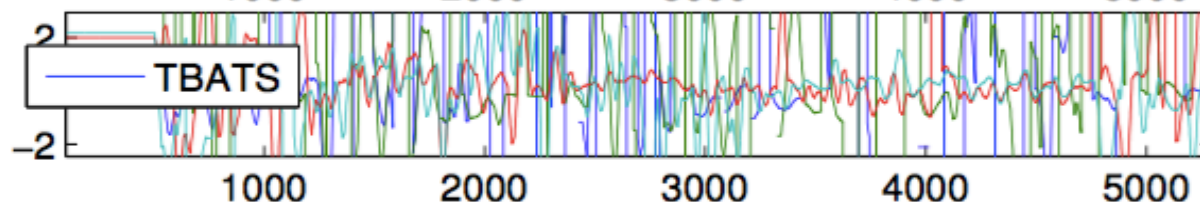
Original
stream



Regime
Cast



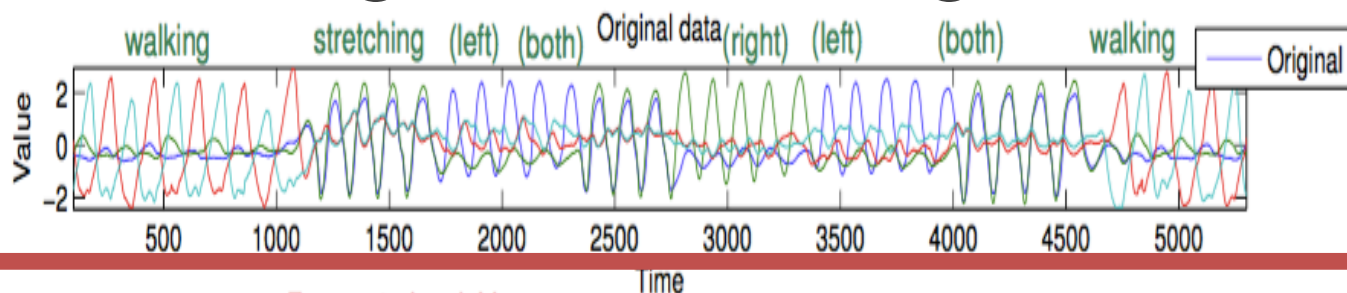
ARIMA



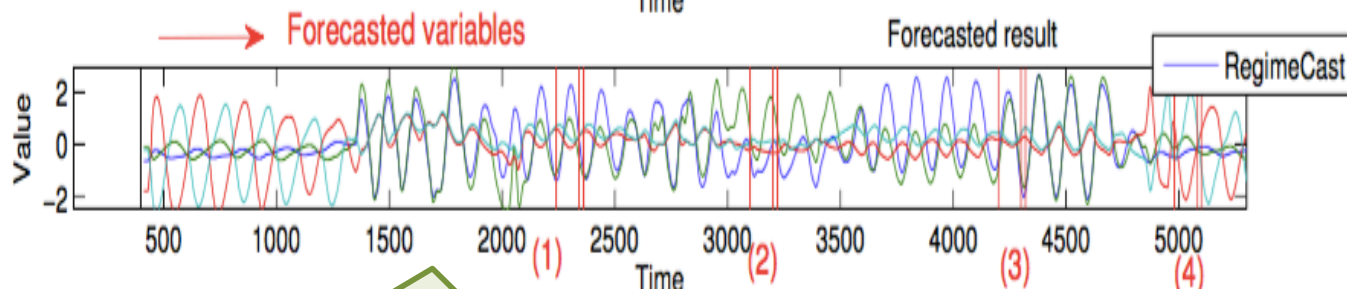
TBATS

Q2. Accuracy

Forecasting results of RegimeCast vs. others



Original
stream



Regime
Cast

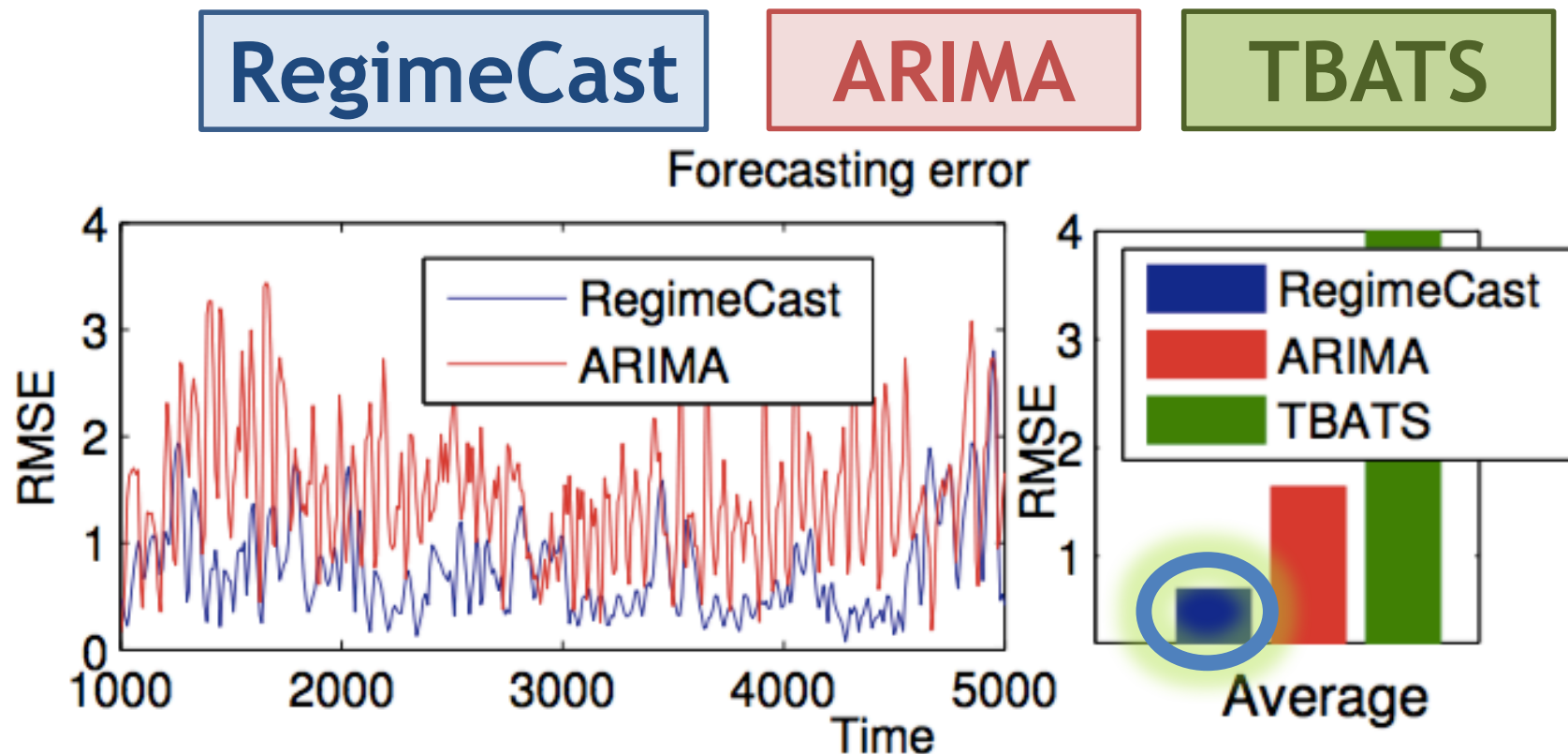
RegimeCast can identify regime-shift dynamics, immediately

ARIMA

TBATS

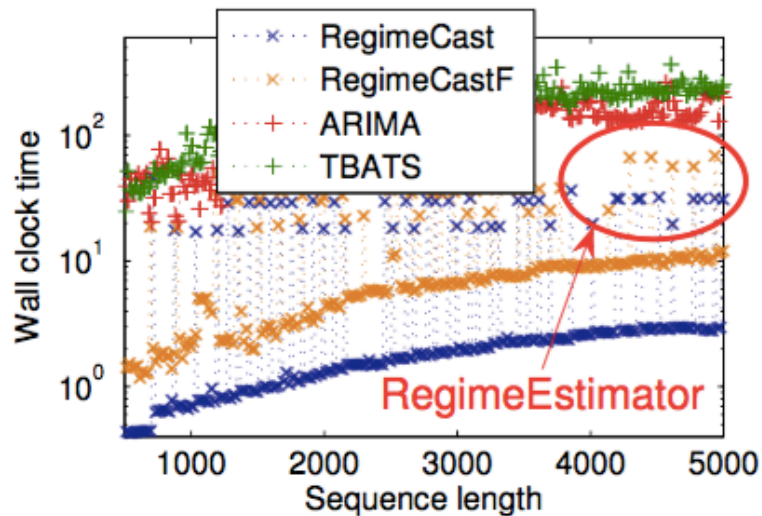
Q2. Accuracy

Forecasting error (RMSE), lower is better

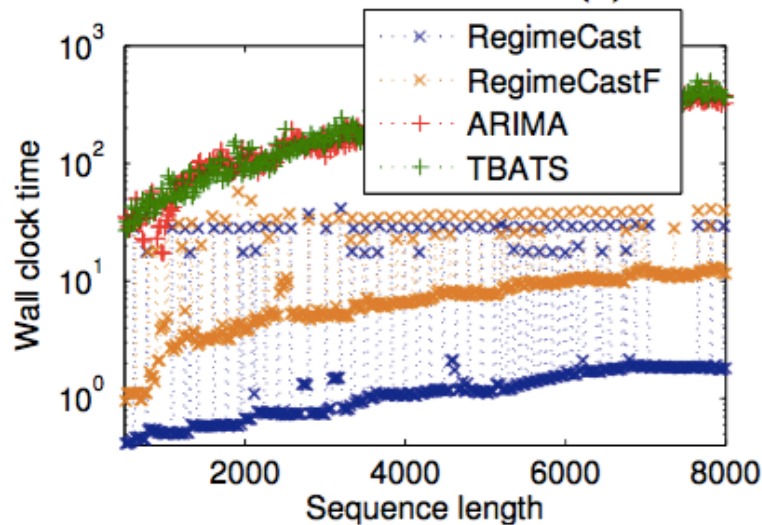


(a) Forecasting error for each time tick (left) and average (right)

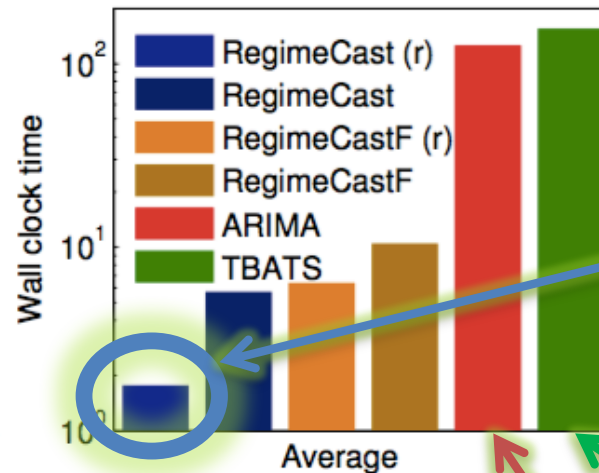
Q3. Scalability



(a) "Exercise"



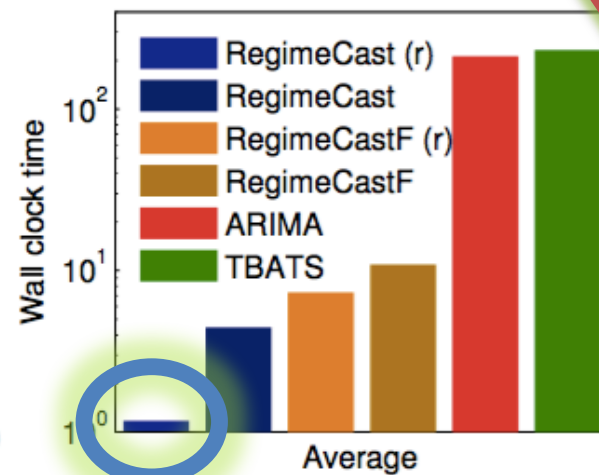
(b) "House-cleaning"



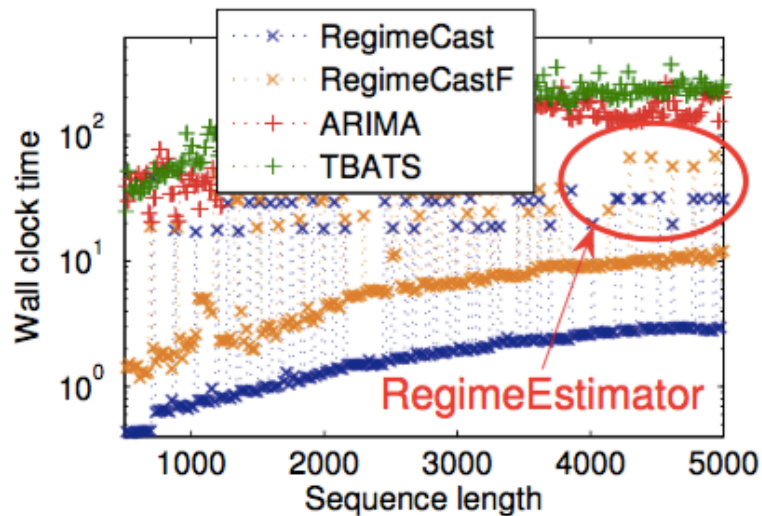
Regime
Cast

TBATS

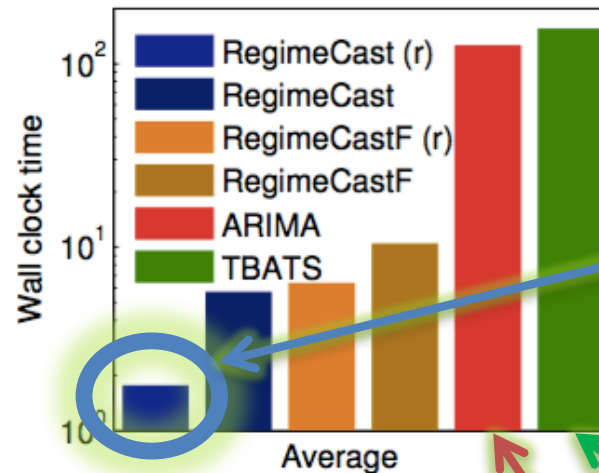
ARIMA



Q3. Scalability

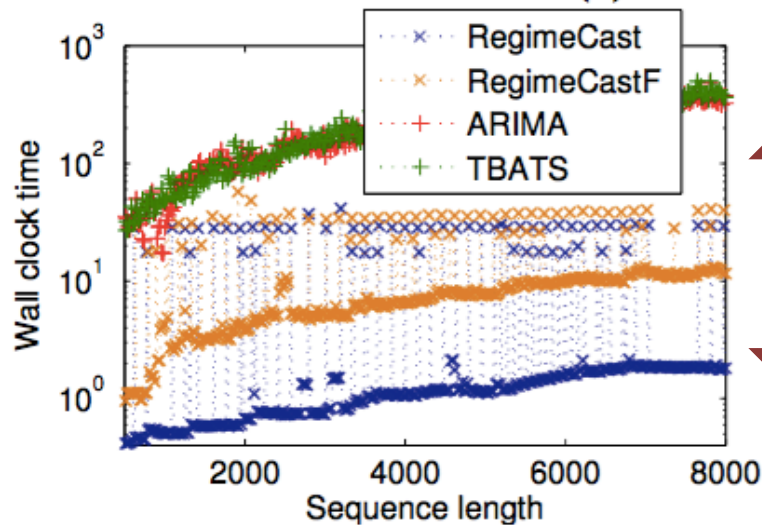


(a) "Exercise"

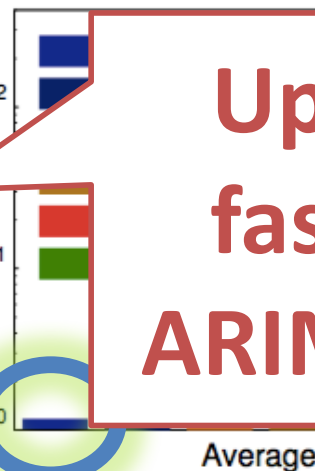


Regime
Cast

TBATS



(b) "House-cleaning"

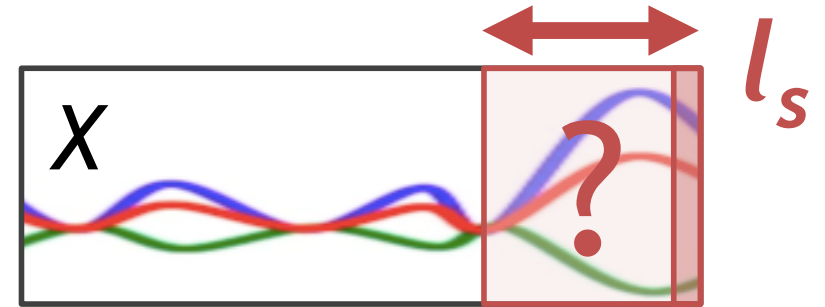


Up to 270x
faster than
ARIMA/TBATS

MA

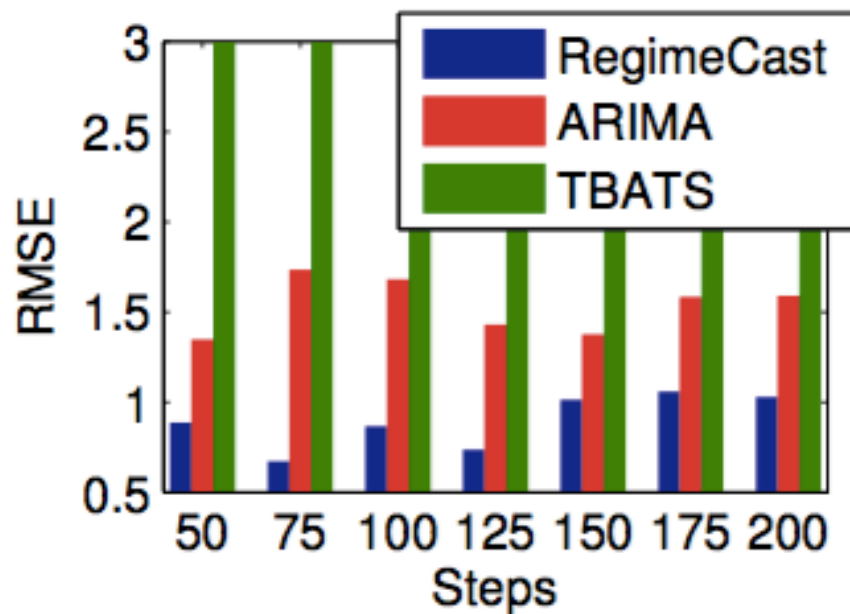
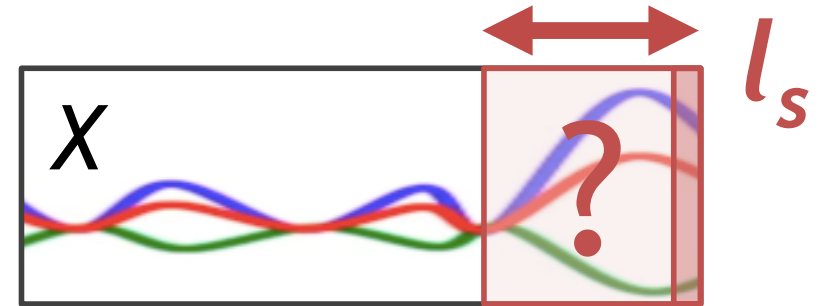
Q. Discussion

Q. How long ahead
can it forecast?

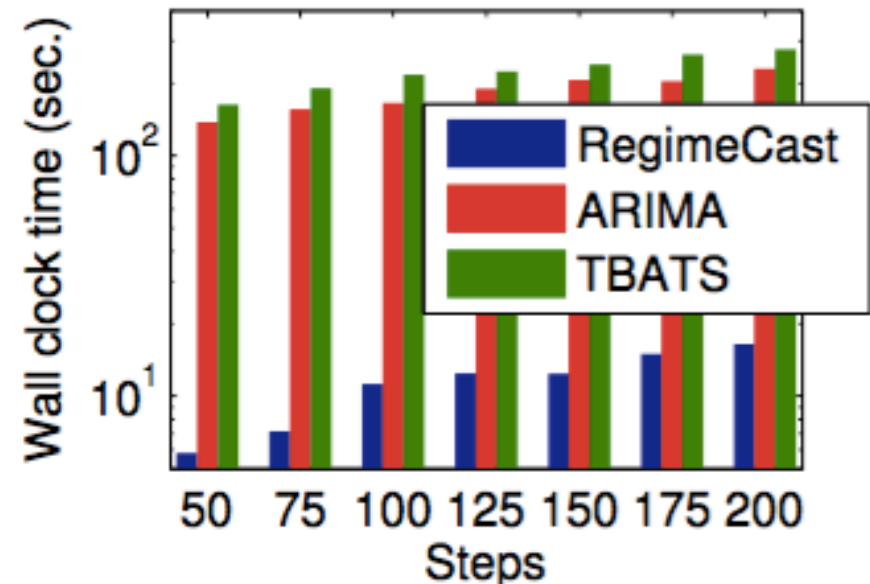


Q. Discussion

Q. How long ahead
can it forecast?



l_s -steps vs. error

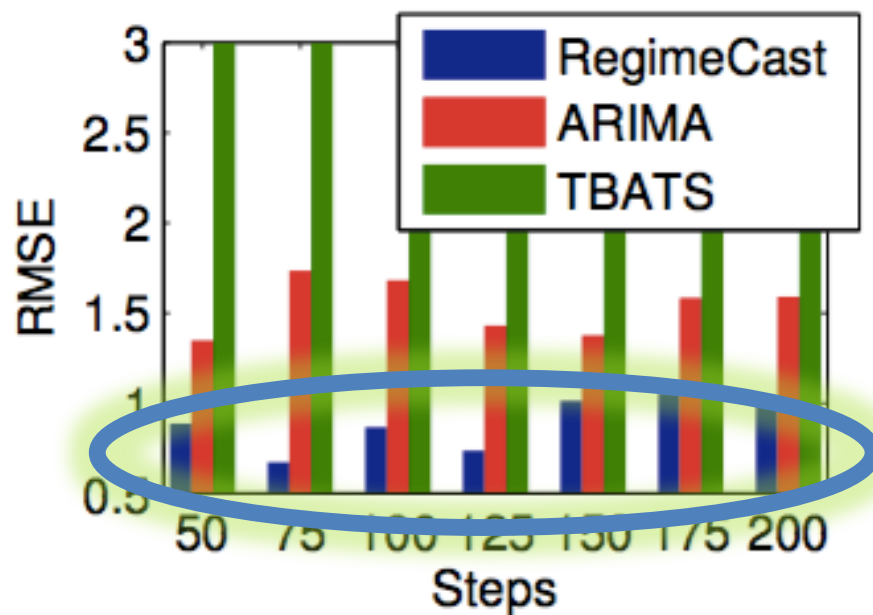


l_s -steps vs. speed

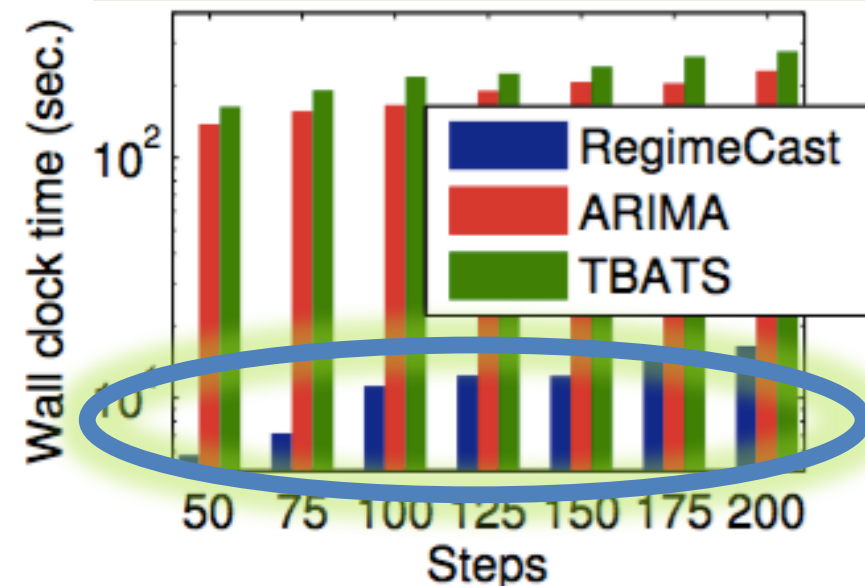
Q. Discussion

Q. How long ahead can it forecast?

A. It can forecast future events for every step l_s



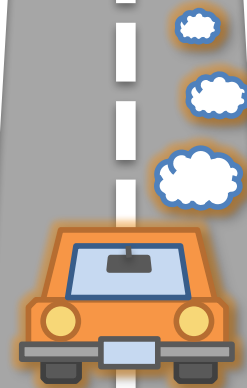
l_s -steps vs. error



l_s -steps vs. speed

Roadmap

- ✓ Motivation
- ✓ Forecasting power of RegimeCast
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Conclusions

RegimeCast has the following advantages

- ✓ **Effective**

Long-term forecasting

- ✓ **Adaptive**

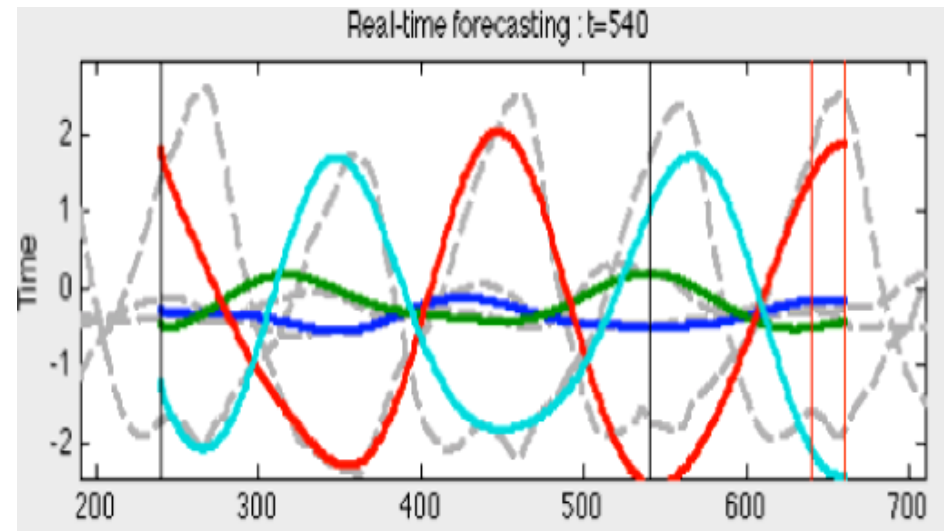
No prior training

- ✓ **Scalable**

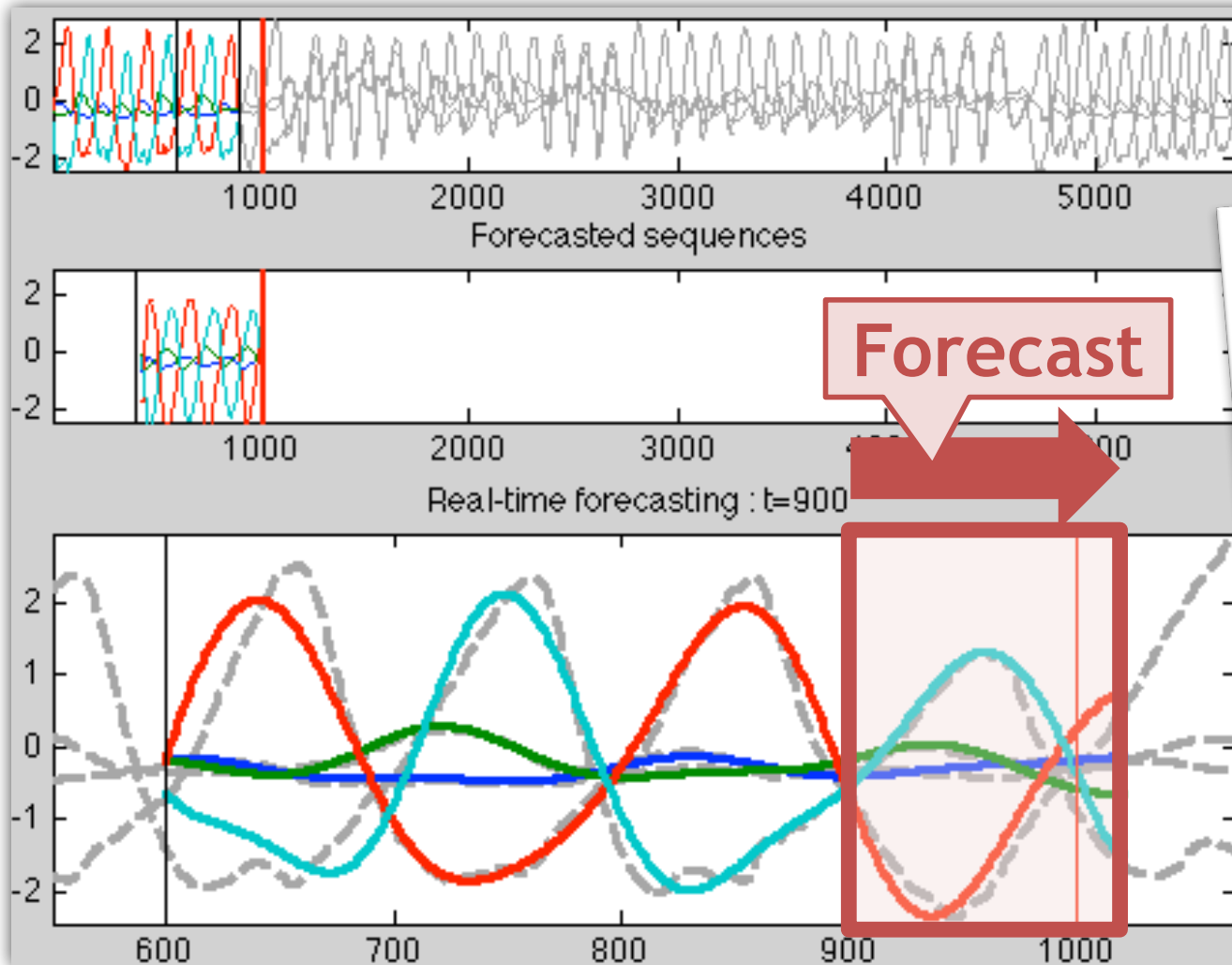
It does not depend on data length

- ✓ **Anytime**

It forecasts future events, immediately, any time



Thank you!



Forecast



Data & Code: <http://www.cs.kumamoto-u.ac.jp/~yasuko>

Regime Shifts in Streams: Real-time Forecasting of Co-evolving Time Sequences

Yasuko Matsubara, Yasushi Sakurai
(Kumamoto University)

